

## INTRODUCTION

### Random Process:

Consider a random experiment with a sample space  $S$ . If a time function  $X(t, s)$  is assigned to each outcome  $s \in S$  and where  $t \in T$ , then the family of all such functions, denoted by  $\{X(t, s)\}$ , where  $s \in S, t \in T$  is called a random process. In other words, a random process is a collection of random variables together with time.

**Note:** A random process is also called stochastic process.

### Classification of Random Process:

Classify a random process according to the characteristic of  $T$  and the state space  $S$ . We shall consider only 4 cases based on  $T$  and  $S$ .

- i) Continuous random process
- ii) Continuous random sequence
- iii) Discrete random process
- iv) Discrete random sequence

### Continuous random Process:

If both  $S$  and  $T$  are continuous, then the random process is called continuous Random process.

### Continuous Random Sequence:

If  $S$  is continuous and  $T$  is discrete, then the random process is called continuous random sequence.

**Discrete Random Process:**

If S is discrete and T is continuous, then the random process is called discrete random process.

**Discrete Random Sequence:**

If both S and T are discrete, then the random process is called discrete random process.

**Deterministic Random Process:**

A random process is called a deterministic random process if all the future values are predicted from past observation.

**Non Deterministic Random Process:**

A random process is called a non - deterministic random process if the future values of any sample function cannot be predicted from the past observation.

**Wide Sense Stationary Process (WSS);**

A process  $\{X(t)\}$  is said to be Wide Sense Stationary Process if

$$(i) \text{Mean} = E[X(t)] = \text{constant}$$

$$(ii) \text{Auto correlation } R_{XX}(\tau) = E[X(t)X(t + \tau)] \text{ depends on } \tau$$

**Note:**

A WSS process is also called as Weak Sense Stationary Process.

A SSS process is also called a strongly stationary process.

For stationary process mean and variance are constants.

A random process, which is not stationary in any sense, is called evolutionary.

**Formulae:****Wide Sense Stationary (WSS):**

$$(i) \text{Mean} = E[X(t)] = \text{constant}$$

$$(ii) \text{Auto correlation } R_{XX}(\tau) = E[X(t)X(t + \tau)] \text{ depends on } \tau$$

**Stationary Process:**

$$(i) E[X(t)] = \text{constant}$$

$$(ii) \text{Var}[X(t)] = \text{constant}$$

**Strict Sense Stationary (SSS):**

$$E[X^n(t)] \text{ is a constant for every } n$$

**Joint Wide Sense Stationary (JWSS):**

$$(i) E[X(t)] = \text{constant}$$

$$(ii) E[Y(t)] = \text{constant}$$

$$(iii) R_{XX}(t, t + \tau) = E[X(t)Y(t + \tau)] \text{ depends on } \tau$$

**Mean Ergodic:**

$$\text{Time average, } \overline{X_T} = \frac{1}{2T} \int_{-T}^T X(t) dt$$

$$E[X(t)] = \lim_{T \rightarrow \infty} \overline{X_T}$$

**Correlation Ergodic:**

$$\overline{X_T} = \frac{1}{2T} \int_{-T}^T X(t) X(t + \tau) dt$$

$$R_{XX}(t, t + \tau) = \lim_{T \rightarrow \infty} \overline{X_T}$$

If  $Y(t) = X(t + a) - X(t - a)$ , prove that  $R_{YY}(\tau) = \langle 2R_{XX}(\tau) - R_{XX}(\tau + 2a) - R_{XX}(\tau - 2a) \rangle$

**Solution:**

Given  $Y(t) = X(t + a) - X(t - a)$

$$R_{YY}(t) = E[Y(t_1)Y(t_2)]$$

$$= E[(X(t_1 + a) - X(t_1 - a))(X(t_2 + a) - X(t_2 - a))]$$

$$= E[(X(t_1 + a)X(t_2 + a) - X(t_1 + a)X(t_2 - a) - X(t_1 - a)X(t_2 + a) + X(t_1 - a)X(t_2 - a))]$$

$$= E[X(t_1 + a)X(t_2 + a)] - E[X(t_1 + a)X(t_2 - a)] - E[X(t_1 - a)X(t_2 + a)] + E[X(t_1 - a)X(t_2 - a)]$$

$$= R_{XX}(t_1 + a, t_2 + a) - R_{XX}(t_1 + a, t_2 - a) - R_{XX}(t_1 - a, t_2 + a) + R_{XX}(t_1 - a, t_2 - a)$$

$$= R_{XX}(t_1 + a - t_2 - a) - R_{XX}(t_1 + a - t_2 + a) - R_{XX}(t_1 - a - t_2 - a) + R_{XX}(t_1 - a - t_2 + a)$$

$$= R_{XX}(t_1 - t_2) - R_{XX}(t_1 - t_2 + 2a) - R_{XX}(t_1 - t_2 - 2a) + R_{XX}(t_1 - t_2)$$

$$= R_{XX}(\tau) - R_{XX}(\tau + 2a) - R_{XX}(\tau - 2a) + R_{XX}(\tau)$$

$$R_{YY}(\tau) = 2R_{XX}(\tau) - R_{XX}(\tau + 2a) - R_{XX}(\tau - 2a)$$

The following formulas are very useful to solve problems under stationary process.

> If  $X$  is a RV with mean zero, then  $\text{Var}(X) = E(X^2)$

$$> 1 + 2x + 3x^2 + \dots = (1 - x)^{-2}$$

$$> 1 + 4x + 9x^2 + \dots = (1 + x)(1 - x)^{-3}$$

> If  $A$  and  $B$  are RV's and  $\lambda$  is a constant, then

$$E[A\cos \lambda t + B\sin \lambda t] = E(A)\cos \lambda t + E(B)\sin \lambda t$$

>  $\therefore E(\cos \lambda \tau) = \cos \lambda \tau$ , since  $\lambda$  and  $\tau$  are constants.

