INTRODUCTION

Random Process:

Consider a random experiment with a sample space S. If a time function X(t, s) is assigned to each outcome $s \in S$ and where $t \in T$, then the family of all such functions, denoted by $\{X(t,s)\}$, where $s \in S$, $t \in T$ is called a random process. In other words, a random process is a collection of random variables together with time.

Note: A random process is also called stochastic process.

Classification of Random Process:

Classify a random process according to the characteristic of T and the state space S. We shall consider only 4 cases based on T and S.

- i) Continuous random process
- ii) Continuous random sequence
- iii) Discrete random process
- iv) Discrete random sequence

Continuous random Process:

If both S and T are continuous, then the random process is called continuous Random process.

Continuous Random Sequence:

If S is continuous and T is discrete, then the random process is called continuous random sequence.

Discrete Random Process:

If S is discrete and T is continuous, then the random process is called discrete random process.

Discrete Random Sequence:

If both S and T are discrete, then the random process is called discrete random process.

Deterministic Random Process:

A random process is called a deterministic random process if all the future values are predicted from past observation.

Non Deterministic Random Process:

A random process is called a non - deterministic random process if the future values of any sample function cannot be predicted from the past observation.

Wide Sense Stationary Process (WSS);

A process $\{X(t)\}$ is said to be Wide Sense Stationary Process if

(i)Mean = E[X(t)] = constant
(ii) Auto correlation R_{XX}(τ) = E[X(t)X(t + τ)] depends on τ

Note:

A WSS process is also called as Weak Sense Stationary Process.

A SSS process is also called a strongly stationary process.

For stationary process mean and variance are constants.

A random process, which is not stationary in any sense, is called evolutionary.

Formulae:

Wide Sense Stationary (WSS):

(i)Mean = E[X(t)] = constant

(ii) Auto correlation $R_{XX}(\tau) = E[X(t)X(t+\tau)]$ depends on τ

Stationary Process:

(i)E[X(t)] = constant(ii)Var[X(t)] = constant

Strict Sense Stationary (SSS):

 $E[X^n(t)]$ is a constant for every n

Joint Wide Sense Stationary (JWSS):

(i)E[X(t)] = constant(ii)E[Y(t)] = constant(iii) $R_{XX}(t, t + \tau) = E[X(t)Y(t + \tau)]$ depends on τ

Mean Ergodic:

Time average,
$$\overline{X_T} = \frac{1}{2T} \int_{-T}^{T} X(t) dt$$

 $E[X(t)] = \lim_{T \to \infty} \overline{X_T}$

Correlation Ergodic:

$$\overline{X_T} = \frac{1}{2T} \int_{-T}^{T} X(t) X(t+\tau) dt$$
$$R_{XX}(t,t+\tau) = \lim_{T \to \infty} \overline{X_T}$$

If
$$Y(t) = X(t + a) - X(t - a)$$
, prove that $R_{YY}(\tau) = \langle 2R_{XX}(\tau) - R_{XX}(\tau + 2a) - R_{XX}(\tau - 2a)$
Solution:
Given $Y(t) = X(t + a) - X(t - a)$
 $R_{YY}(t) = E[Y(t_1)Y(t_2)]$
 $= E[(X(t_1 + a) - X(t_1 - a)(X(t_2 + a) - X(t_2 - a))]$
 $= E[(X(t_1 + a)(X(t_2 + a) - X(t_1 + a)X(t_2 - a) - X(t_1 - a)(X(t_2 + a) + X(t_1 - a)X(t_2 - a))]$
 $= E[X(t_1 + a)(X(t_2 + a)] - E[X(t_1 + a)X(t_2 - a)] - E[X(t_1 - a)(X(t_2 + a)] + E[X(t_1 - a)X(t_2 - a)]]$
 $= R_{XX}(t_1 + a, t_2 + a) - R_{XX}(t_1 + a, t_2 - a) - R_{XX}(t_1 - a, t_2 + a) + R_{XX}(t_1 - a, t_2 - a)$
 $= R_{XX}(t_1 + a - t_2 - a) - R_{XX}(t_1 + a - t_2 + a) - R_{XX}(t_1 - a - t_2 - a)$
 $+ R_{XX}(t_1 - a - t_2 + a)$
 $= R_{XX}(t_1 - t_2) - R_{XX}(t_1 - t_2 + 2a) - R_{XX}(t_1 - t_2 - 2a) + R_{XX}(t_1 - t_2)$
 $= R_{XX}(\tau) - R_{XX}(\tau + 2a) - R_{XX}(\tau - 2a) + R_{XX}(\tau)$
 $= R_{YY}(\tau) = 2R_{XX}(\tau) - R_{XX}(\tau + 2a) - R_{XX}(\tau - 2a)$
The following formulas are very useful to solve problems under stationary process.

> If X is a RV with mean zero, then $Var(X) = E(X^2)$

> 1 + 2x + 3x² + ... =
$$(1 - x)^{-2}$$

> 1 + 4x + 9x² + ... = $(1 + x)(1 - x)^{-3}$

> If *A* and *B* are RV's and λ is a constant, then

 $E[A\cos\lambda t + B\sin\lambda t] = E(A)\cos\lambda t + E(B)\sin\lambda t$

> $\therefore E(\cos \lambda \tau) = \cos \lambda \tau$, since λ and τ are constants.

STATIONARY PROCESS

Problems under Stationary process:

For a stationary process

- (1) E[X(t)] is a constant
- (2) Var[X(t)] is a constant
- **1.** The process $\{X(t)\}$ whose probability distribution unde certain

conditions is given by $P[X(t) = n] = \begin{cases} \frac{(at)^{n-1}}{(1+at)^{(n+1)}}; n = 1, 2, 3, \dots, \\ \frac{at}{1+at}; n = 0 \end{cases}$

Show that it is not a stationary process (Evolutionary).

Solution:

| | 100 | UBSERVE OF | | DREAD | |
|----------|-------------------|----------------------|-----------------------|---------------------------|--|
| п | 0 < | 1 | 2 | 3 | |
| | | | | | |
| $p_n(t)$ | $\frac{at}{1+at}$ | $\frac{1}{(1+at)^2}$ | $\frac{at}{(1+at)^3}$ | $\frac{(at)^2}{(1+at)^4}$ | |
| | | | | | |

For a stationary process,

(1) E[X(t)] is a constant

(2) Var[X(t)] is a constant

$$\begin{split} E[X(t)] &= \sum_{n=0}^{\infty} np_n(t) = 0 + \frac{1}{(1+at)^2} + (2)\frac{at}{(1+at)^3} + (3)\frac{(at)^2}{(1+at)^4} \\ &= \frac{1}{(1+at)^2} \Big[1 + 2\frac{at}{1+at} + 3\frac{(at)^2}{(1+at)^2} + \cdots \dots \Big] \\ &= \frac{1}{(1+at)^2} \Big[1 - \frac{at}{(1+at)} \Big]^{-2} \\ &= \frac{1}{(1+at)^2} \Big[\frac{1+at-at}{(1+at)} \Big]^{-2} \\ &= \frac{1}{(1+at)^2} \Big[\frac{1}{(1+at)} \Big]^{-2} \\ &= \frac{1}{(1+at)^2} \Big[\frac{1}{(1+at)} \Big]^{-2} \end{split}$$

E[X(t)] = 1 which is a constant

$$\begin{split} \mathrm{E}[\mathrm{X}^{2}(\mathrm{t})] &= \sum_{n=1}^{\infty} n^{2} p_{n}(t) = 0 + \frac{1}{(1+at)^{2}} + (4) \frac{at}{(1+at)^{3}} + (9) \frac{(at)^{2}}{(1+at)^{4}} + \cdots \\ &= \frac{1}{(1+at)^{2}} \Big[1 + 4 \frac{at}{1+at} + 9 \frac{(at)^{2}}{(1+at)^{2}} + \cdots \Big] \\ &= \frac{1}{(1+at)^{2}} \Big(1 + \frac{at}{1+at} \Big) \Big[1 - \frac{at}{1+at} \Big] \\ &= \frac{1}{(1+at)^{2}} \Big(\frac{1+2at}{1+at} \Big) (1+at)^{3} \end{split}$$

 $E[X^{2}(t)] = 1 + 2at$, which is not a constant

Var $[X(t)] = E[X^{2}(t)] - [E[X(t)]]^{2} = 1 + 2at - 1$

= 2at which is not a constant.

 \therefore {*X*(*t*)} is not a stationary process.

2. Consider a random process A_1 and A_2 are independent random

variables with $E(A_i) = a_i$ and $Var(A_i) = \sigma_i^2$ for i = 1, 2 Prove that the process $\{X(t)\}$ is evolutionary.

Solution:

Given $X(t) = A_1 + A_1 t$ where A_1 and A_2 are independent random variables with $E(A_i) = a_i$ and $Var(A_i) = \sigma_i^2$ for i = 1,2

For a stationary process

(1) E[X(t)] is a constant

(2) Var[X(t)] is a constant

 $E[X(t)] = E[A_1 + A_1 t]^{OBSERVE} OPTIMIZE OUTSPREE$

$$= E[A_1] + tE[A_2]$$

$$=a_1+ta_2$$

Which is not a constant.

Thus, the process $\{X(t)\}$ is evolutionary.

3. Let $X(t) = B\sin \omega t$, where B is a random variable with mean and

variance 1 and ω is a constant. Check whether $\{X(t)\}$ is a stationary or not

Solution:

Given $X(t) = B\sin \omega t$, where

B is a random variable with Mean=0 and Variance =1

Mean of $B = 0 \Rightarrow E(B) = 0$ (i)

Variance of $B = 1 \Rightarrow E(B^2) = 1 \dots \dots \dots$ (ii)

For a stationary process,

(1) E[X(t)] is a constant

(2) Var[X(t)] is a constant

(1)
$$E[X(t)] = E[B\sin\omega t]$$

 $= E[B]\sin\omega t$

= 0 From (i)

 $\therefore E[X(t)]$ is a constant

(2)
$$E[X^{2}(t)] = E[B^{2}\sin^{2}\omega t]$$

= $E(B^{2})\sin^{2}\omega t$
= $\sin^{2}\omega t$ which is not a constant From (*ii*)

 $\operatorname{Var}[X(t)] = E[X^2(t)] - [E[X(t)]^2] = \sin^2 \omega t$, which is not a constant.

Since the condition (2) for Stationary Process is not satisfied,

Hence $\{X(t)\}$ is not a Stationary Process.

4. Consider the random process $X(t) = \cos(t + \varphi)$ where φ is a random variable with density function $f(\varphi) = \frac{1}{\pi}$, where $-\frac{\pi}{2} < \varphi < \frac{\pi}{2}$. Check whether or not the process is stationary.

Solution:

$$X(t) = \cos(t + \varphi)$$
 where φ is a random variable with

$$f(\varphi) = \frac{1}{\pi}$$
, where $-\frac{\pi}{2} < \varphi < \frac{\pi}{2}$

For a stationary process,

(1)E[X(t)] is a constant

(2) Var[X(t)] is a constant

$$E[X(t)] = E[\cos(t + \varphi)]$$

$$=\int_{\frac{\pi}{2}}^{\frac{\pi}{2}}\cos(t+\varphi)f(\varphi)d\varphi$$

$$=\int_{\frac{\pi}{2}}^{\frac{\pi}{2}}\cos(t+\varphi)\frac{1}{\pi}d\varphi$$

$$=\frac{1}{\pi}\int_{-\frac{\pi}{2}}^{\frac{\pi}{2}}\cos(t+\varphi)d\varphi$$

$$= \frac{1}{\pi} [\sin(t+\varphi)]_{-\frac{\pi}{2}}^{\frac{\pi}{2}}$$

$$= \frac{1}{\pi} \left[\sin\left(t+\frac{\pi}{2}\right) - \sin\left(t-\frac{\pi}{2}\right) \right]$$

$$= \frac{1}{\pi} \left[\sin\left(\frac{\pi}{2}+t\right) + \sin\left(\frac{\pi}{2}-t\right) \right]$$

$$\therefore \sin\left(\frac{\pi}{2}-\theta\right) = \sin\left(\frac{\pi}{2}+\theta\right) = \cos\theta$$

$$= \frac{1}{\pi} [\cos t + \cos t]$$

$$= \frac{1}{\pi} 2\cos t$$

 $E[X(t)] = \frac{1}{\pi} 2\cos t$, which depends on t.

Since the condition (1) for Stationary Process is not satisfied,

 $\{X(t)\}$ is not a Stationary Process.

5. Let $X(t) = \cos(\omega t + \theta)$, where θ is a random variable uniformly distributed over $(0, 2\pi)$. Prove that $\{X(t)\}$ is a stationary process of first order.

Solution:

Given: $X(t) = \cos(\omega t + \theta)$, where θ is random variable uniformly distributed over $(0, 2\pi)$.

$$\therefore f_{\theta}(\theta) = \frac{1}{2\pi}; 0 < \theta < 2\pi$$

To prove $\{X(t)\}$ is a first order stationary process.

we have to prove $f_X(x; t)$ is independent of time.

To find $f_X(x; t)$:

We have $x = \cos(\omega t + \theta)$ $\Rightarrow \omega t + \theta = \pm \cos^{-1}[x]$ To find $f_X(x; t)$, Take x = X(t) $\Rightarrow \theta = -\omega t \pm \cos^{-1}[x] \because \cos[\pm(\omega t + \theta)] = \cos(\omega t + \theta)$ Let $\theta_1 = -\omega t - \cos^{-1} x$ and $\theta_2 = -\omega t + \cos^{-1} x$ $\frac{d\theta_1}{dx} = 0 - \frac{-1}{\sqrt{1 - x^2}} = \frac{1}{\sqrt{1 - x^2}}$

The first order density of $\{X(t)\}$ is given by

$$f_x(x,t) = \left| \frac{d\theta_1}{dx} \right| f_\theta(\theta_1) + \left| \frac{d\theta_2}{dx} \right| f_\theta(\theta_2)$$
$$= \left| \frac{1}{\sqrt{1-x^2}} \right| \frac{1}{2\pi} + \left| \frac{-1}{\sqrt{1-x^2}} \right| \frac{1}{2\pi}$$

$$= \frac{1}{2\pi} \frac{1}{\sqrt{1-x^2}} + \frac{1}{2\pi} \frac{1}{\sqrt{1-x^2}}$$

$$=\frac{2}{2\pi}\frac{1}{\sqrt{1-x^2}}$$

$$f_X(x,t) = \frac{1}{\pi} \frac{1}{\sqrt{1-x^2}}$$

To find the range of *x* :

We have $x = X(t) = \cos(\omega t + \theta)$.

Since the value of $\cos(\omega t + \theta)$ lies between -1 and +1, we have $-1 \le x \le 1$.

$$\therefore f_X(x,t) = \frac{1}{\pi} \frac{1}{\sqrt{1-x^2}}, -1 \le x \le 1 \dots \dots (1)$$

which is independent of time.

Hence, $\{X(t)\}$ is a stationary process of first order.

Problems on Wide Sense Stationary (WSS):

1. Show that the random process $X(t) = A \cos(\omega t + \theta)$ is WSS, where

A and ω are constants and θ is uniformly distributed on the interval

 $(0, 2\pi)$

Solution:

Given, $X(t) = A\cos(\omega t + \theta)$

 θ is uniformly distributed on the interval (0, 2π)

$$f(\theta) = \frac{1}{b-a}, a < \theta < b$$
$$f(\theta) = \frac{1}{2\pi}, 0 < \theta < 2\pi$$

To Prove X(t) is WSS.

(i)Mean = E[X(t)] = constant

(ii) Auto correlation $R_{XX}(\tau) = E[X(t)X(t+\tau)]$ depends on τ

(i)
$$E[X(t)] = \int_{-\infty}^{\infty} X(t) f(\theta) d\theta$$

 $= \int_{0}^{2\pi} A \cos(\omega t + \theta) \frac{1}{2\pi} d\theta$
 $= \frac{A}{2\pi} [\sin(\omega t + \theta)]_{0}^{2\pi}$
 $= \frac{A}{2\pi} [\sin(\omega t + 2\pi) - \sin(\omega t + \theta)]$
 $= \frac{A}{2\pi} [\sin \omega t - \sin \omega t] = 0$
 $E[X(t)] = 0 \text{ is constant.}$
(ii) $R_{XX}(\tau) = E[X(t)X(t + \tau)]$
 $= E[A \cos(\omega t + \theta) A \cos(\omega(t + \tau) + \theta)]$

 $= E[A^{2}]E[\cos(\omega t + \theta)\cos(\omega(t + \tau) + \theta)]$

 $=A^{2}\frac{1}{2}E[\cos(\omega t+\theta+\omega t+\omega \tau+\theta)\cos(\omega t+\theta-\omega t-\omega \tau-\theta)]$

$$cos(-\theta) = cos \theta$$

$$cos A cos B = \frac{1}{2} [cos(A + B) + cos(A - B)]$$

$$= A^2 \frac{1}{2} E[cos(2\omega t + 2\theta + \omega \tau) cos(-\omega \tau)]$$

$$= \frac{A^2}{2} E[cos(2\omega t + 2\theta + \omega \tau) cos(\omega \tau)]$$

$$= \frac{A^2}{2} [cos \omega \tau + \int_0^{2\pi} cos(2\omega t + 2\theta + \omega \tau) \frac{1}{2\pi} d\theta]$$

$$= \frac{A^2}{2} cos \omega \tau + \frac{A^2}{4\pi} \left[\frac{sin(2\omega t + 2\theta + \omega \tau)}{2} \right]_0^{2\pi}$$

$$= \frac{A^2}{2} cos \omega \tau + \frac{A^2}{8\pi} [sin(2\omega t + \omega \tau + 4\pi) - sin(2\omega t + \omega \tau)]$$

$$= \frac{A^2}{2} cos \omega \tau + \frac{A^2}{8\pi} [sin(2\omega t + \omega \tau) - sin(2\omega t + \omega \tau)]$$

$$= \frac{A^2}{2} cos \omega \tau + \frac{A^2}{8\pi} [0]$$

$$R_{XX}(\tau) = \frac{A^2}{2} cos \omega \tau$$

Hence X(t) is WSS process.

2.Show that the random process $X(t) = A \cos \lambda t + B \sin \lambda t$ where λ is a constant, A and B are random variables, is WSS if (i) E[A] = E[B] = 0(ii) $E[A^2] = E[B^2]$ and (iii) E[AB] = 0

Solution:

Given, $X(t) = A \cos \lambda t + B \sin \lambda t$

$$E[A] = E[B] = 0$$
, $E[A^2] = E[B^2]$, $E[AB] = 0$

To Prove X(t) is WSS.

(i)Mean = E[X(t)] = constant

(ii) Auto correlation $R_{XX}(\tau) = E[X(t)X(t+\tau)]$ depends on τ

(i) $E[X(t)] = E[A \cos \lambda t + B \sin \lambda t]$

 $= E[A] \cos \lambda t + E[B] \sin \lambda t$

 $= 0 * \cos \lambda t + 0 * \sin \lambda t$

E[X(t)] = 0 is constant.

(ii) $R_{XX}(\tau) = E[X(t)X(t+\tau)]$

 $= E[(A \cos \lambda t + B \sin \lambda t)(A \cos \lambda(t + \tau) + B \sin \lambda(t + \tau))]$ $= E[A^{2} \cos \lambda t \cos \lambda(t + \tau) + AB \cos \lambda t \sin \lambda(t + \tau)$ $+ AB \sin \lambda t \cos \lambda(t + \tau) + B^{2} \sin \lambda t \sin \lambda(t + \tau)]$

 $= E[A^{2} \cos \lambda t \cos \lambda (t + \tau)] + E[AB \cos \lambda t \sin \lambda (t + \tau)] + E[AB \sin \lambda t \cos \lambda (t + \tau)] + E[B^{2} \sin \lambda t \sin \lambda (t + \tau)]$

$$= E[A^2 \cos \lambda t \, \cos \, \lambda(t+\tau)] + E[B^2 \sin \lambda t \, \sin \lambda(t+\tau)]$$

$$= E[A^2] \cos \lambda t \, \cos \, \lambda(t+\tau) \, + E[B^2] \sin \lambda t \, \sin \lambda(t+\tau)$$

$$= k \cos \lambda t \cos \lambda (t + \tau) + k \sin \lambda t \sin \lambda (t + \tau)$$

$$= k[\cos \lambda t \cos \lambda (t + \tau) + \sin \lambda t \sin \lambda (t + \tau)]$$

$$= k[\cos(\lambda t - \lambda t - \lambda \tau)]$$

$$\cos(-\theta) = \cos \theta$$

$$\cos A \cos B + \sin A \sin B = \cos(A - B)$$

$$= k[\cos(-\lambda \tau)]$$

$$= k[\cos(\lambda \tau)]$$

Hence X(t) is WSS process.

3. Given a random variable y with characteristic function $\varphi(\omega) =$

 $E[e^{i\omega y}]$ and a random process $X(t) = \cos(\lambda t + y)$. Show that X(t) is

stationary in the wide sense if $\varphi(1) = \varphi(2) = 0$

Solution:

DBSERVE OPTIMIZE OUTSPREAD

Given, $X(t) = \cos(\lambda t + y)$

$$\varphi(\omega) = E[e^{i\omega y}] = E[\cos \omega y + i \sin \omega y]$$

 $= E[\cos \omega y] + i E[\sin \omega y]$

Given, $\varphi(1) = 0$

 $\Rightarrow 0 = E[\cos y] + i E[\sin y]$

 $E[\cos y] = 0; E[\sin y] = 0$

Given, $\varphi(2) = 0$

$$\Rightarrow 0 = E[\cos 2y] + i E[\sin 2y]$$

 $E[\cos 2y] = 0; E[\sin 2y] = 0$

To Prove X(t) is WSS.

(i)Mean = E[X(t)] = constant

(ii) Auto correlation $R_{XX}(\tau) = E[X(t)X(t+\tau)]$ depends on τ

(i) $E[X(t)] = E[\cos(\lambda t + y)]$

 $= E[\cos \lambda t \, \cos y \, - \sin \lambda t \, \sin y]$

 $\cos(A+B) = \cos A \cos B - \sin A \sin B$

 $\cos A \cos B = \frac{1}{2} [\cos(A+B) + \cos(A-B)]$

 $= \cos \lambda t \ E[\cos y] - \sin \lambda t \ E[\sin y]$

$$l = \cos \lambda t * 0 - \sin \lambda t * 0$$

E[X(t)] = 0 is constant.

(ii) $R_{XX}(\tau) = E[X(t)X(t+\tau)]$ $= E[\cos (\lambda t + y) \cos (\lambda (t+\tau) + y)]$ $= E[\cos (\lambda t + y) \cos (\lambda t + \lambda \tau + y)]$ $= \frac{1}{2}E[\cos(\lambda t + y + \lambda t + \lambda \tau + y) + \cos(\lambda t + y - \lambda t - \lambda \tau - y)]$

$$=\frac{1}{2}E[\cos(2\lambda t + 2y + \lambda\tau) + \cos(-\lambda\tau)]$$

$$=\frac{1}{2}\cos\lambda\tau + \frac{1}{2}E[\cos(2\lambda t + \lambda\tau)\cos 2y - \sin(2\lambda t + \lambda\tau)\sin 2y]$$

$$=\frac{1}{2}\cos\lambda\tau + \frac{1}{2}\cos(2\lambda t + \lambda\tau)E[\cos 2y] - \frac{1}{2}\sin(2\lambda t + \lambda\tau)E[\sin 2y]$$

$$= \frac{1}{2}\cos\lambda\tau + \frac{1}{2}(0)$$
$$R_{XX}(\tau) = \frac{1}{2}\cos\lambda\tau$$

Hence $\{X(t)\}$ is WSS process.

4. Show that the process $X(t) = Y \cos \omega t + Z \sin \omega t$ where Y and Z

independent RV's which follows $N(0, \sigma^2)$ and ω is a constant, is wide sense stationary.

Solution:

VESERVE OPTIMIZE OUTSPREAU

Given $X(t) = Y \cos \omega t + Z \sin \omega t$, where Y and Z are independent

- $(\mathbf{i})E(Y) = E(Z) = 0$
- (ii) E(YZ) = 0

(iii) $E(Y^2) = E(Z^2) = \sigma^2$

To prove $\{X(t)\}$ is a WSS process,

(1) E[X(t)] is a constant

- (2) $R_{XX}(t_1, t_2)$ is a function of τ
- (1) $E[X(t)] = E[Y\cos\omega t + Z\sin\omega t]$

 $= E(Y)\cos\omega t + E(Z)\sin\omega t$

= 0 + 0 = 0 From (i)

 $\therefore E[X(t)]$ is a constant

(2) $R_{XX}(t_1, t_2) = E[X(t_1)X(t_2)]$

 $= E[(Y\cos\omega t_1 + Z\sin\omega t_1)(Y\cos\omega t_2 + Z\sin\omega t_2)]$

 $= E[Y^2 \cos \omega t_1 \cos \omega t_2 + YZ \sin \omega t_2 \cos \omega t_1 + ZY \sin \omega t_1 \cos \omega t_2$

 $+Z^2\sin\omega t_1\sin\omega t_2$]

 $= E(Y^2)\cos\omega t_1\cos\omega t_2 + E(YZ)\sin\omega t_2\cos\omega t_1 + E(YZ)\sin\omega t_1\cos\omega t_2$

 $+E(Z^2)\sin\omega t_1\sin\omega t_2$

$$= \sigma^2 \cos \omega t_1 \cos \omega t_2 + 0 + 0 + 0$$

 $\sigma^2 \sin \omega t_1 \sin \omega t_2$ From (ii) & (iii)

 $= \sigma^2 [\cos \omega t_1 \cos \omega t_2 + \sin \omega t_1 \sin \omega t_2]$

$$=\sigma^2\cos(\omega t_1 - \omega t_2)$$

$$= \sigma^2 \cos[\omega(t_1 - t_2)]$$

 $R_{XX}(t_1, t_2) = \sigma^2 \cos \omega \tau$

 $R_{XX}(t_1, t_2)$ is a function of τ .

Since the conditions (1) and (2) for WSS are satisfied.

Hence, $\{X(t)\}$ is a WSS Process.

5. If $X(t) = Y \cos t + Z \sin t$, where Y and Z are independent binary random variables each of which assumes the values -1 and +2 with probabilities $\frac{2}{3}$ and $\frac{1}{3}$ respectively. Prove that $\{X(t)\}$ is WSS.

Solution:

Given $X(t) = Y \cos t + Z \sin t$, where Y and Z are independent binary random variables. The probability distribution of Y and Z are given by

| У | -1 | 2 | Z | -1 | 20 |
|------|-----|-----|-----|-------|-----|
| P(y) | 2/3 | 1/3 | P(z |) 2/3 | 1/3 |

$$E(Y) = \sum yp(y) = (-1)\left(\frac{2}{3}\right) + 2\left(\frac{1}{3}\right)$$

SERVE OPTIMIZE OUTSPREAD

E(Y) = 0

$$E(Y^2) = \sum y^2 p(y) = 1\left(\frac{2}{3}\right) + 4\left(\frac{1}{3}\right)$$

$$=\frac{2}{3}+\frac{4}{3}$$

 $=\frac{6}{2}=2$

Similarly, $E(Z) = 0, E(Z^2) = 2$.

Since, Y and Z are independent, E(YZ) = E(Y)E(Z) = 0

To prove $\{X(t)\}$ is a WSS process

(1) E[X(t)] is a constant

(2) $R_{XX}(t_1, t_2)$ is a function of n of τ

(1) $E[X(t)] = E[Y\cos t + Z\sin t]$ GINEER

 $= E(Y)\cos t + E(Z)\sin t = 0$

 $\therefore E[X(t)]$ is a constant.

(2)
$$R_{XX}(t_1, t_2) = E[X(t_1)X(t_2)]$$

 $= E[(Y\cos t_1 + Z\sin t_1)(Y\cos t_2 + Z\sin t_2)]$
 $= E[Y^2\cos t_1\cos t_2 + YZ\sin t_2\cos t_1 + YZ\sin t_1\cos t_2 + Z^2\sin t_1\sin t_2]$
 $= E(Y^2)\cos t_1\cos t_2 + E(YZ)\sin t_2\cos t_1 + E(YZ)\sin t_1\cos t_2$
 $+E(Z^2)\sin t_1\sin t_2$
 $= 2\cos t_1\cos t_2 + 2\sin t_1\sin t_2$
 $= 2\cos(t_1 - t_2) = 2\cos \tau$

 $R_{XX}(t_1, t_2)$ is a function of τ .

Since the conditions (1) and (2) for WSS are satisfied.

Hence, $\{X(t)\}$ is a WSS Process.

6. Consider the process $X(t) = \sum_{i=1}^{n} (A_i (A_i \cos p_i t + B_i \sin p_i t))$ where A_i

and B_i are uncorrelated R.v's with mean' 0 ' & variance σ_i^2 . Prove that

 $\{X(t)\}$ is a WSS process.

Solution:

Given $X(t) = \sum_{i=1}^{n} (A_i \cos p_i t + B_i \sin p_i t)$

 A_i and B_i are Rv's

Given Means of A_i and $B_i = 0 \Rightarrow E[A_i] = 0 \& E[B_i] = 0$ and

 $\operatorname{Var}[A_i] = \operatorname{Var}[B_i] = \sigma_i^2$ $\Rightarrow E[A_i^2] = E[B_i^2] = \sigma_i^2$

Also A_i and B_i are uncorrelated $\therefore E[A_iB_j] = 0$ for all i, j

 $\therefore E[A_i A_j] = E[B_i B_j] = 0 \text{ for } i \neq j$

To prove $\{X(t)\}$ is a WSS process

- (1) E[X(t)] is a constant ESERVE OPTIMIZE OUTSPREAD
- (2) $R_{XX}(t_1, t_2)$ is a function of τ .

(1)
$$E[X(t)] = E[\sum_{i=1}^{n} (A_i \cos p_i t + B_i \sin p_i t)]$$

= $\sum_{i=1}^{n} [E(A_i) \cos p_i t + E(B_i) \sin p_i t] = 0$

 $\therefore E[X(t)]$ is a constant.

2) The ACF of {X(t)} is given by
$$R(\tau) = E[X(t_1)X(t_2)]$$

$$= E[\sum_{i=1}^{n} (A_i \cos p_i t_1 + B_i \sin p_i t_1) \sum_{j=1}^{n} (A_j \cos p_j t_2 + B_j \sin p_j t_2)]$$

$$= E[\sum_{i=1}^{n} \sum_{j=1}^{n} (A_i \cos p_i t_1 + B_i \sin p_i t_1) (A_j \cos p_j t_2 + B_j \sin p_j t_2)]$$

$$= E[\sum_{i=1}^{n} \sum_{j=1}^{n} [[A_i A_j \cos p_i t_1 \cos p_j t_2 + A_i B_j \cos p_i t_1 \sin p_j t_2 + A_j B_i \sin p_i t_1 \cos p_i t_1 \sin p_j t_2)]$$

$$= \sum_{i=1}^{n} \sum_{j=1}^{n} [[E(A_i A_j) \cos p_i t_1 \cos p_j t_2 + E(A_i B_j) \cos p_i t_1 \sin p_j t_2 + E(A_j B_i) \sin p_i t_1 \cos p_i t_2 + E(B_i B_j) \sin p_i t_1 \sin p_j t_2)]$$

$$= \sum_{i=1}^{n} \sum_{j=1}^{n} [E(A_i A_j) \cos p_i t_1 \cos p_j t_2 + E(B_i B_j) \sin p_i t_1 \sin p_j t_2)]$$

$$= \sum_{i=1}^{n} \sum_{j=1}^{n} [E(A_i A_j) \cos p_i t_1 \cos p_j t_2 + E(B_i B_j) \sin p_i t_1 \sin p_j t_2)]$$

$$= \sum_{i=1}^{n} [E(A_i)^2 \cos p_i t_1 \cos p_j t_2 + E(B_i)^2 \sin p_i t_1 \sin p_j t_2)]$$

$$= \sum_{i=1}^{n} \sigma_i^2 (\cos p_i t_1 \cos p_i t_2 + \sin p_i t_1 \sin p_i t_2) = \sum_{i=1}^{n} \sigma_i^2 \cos(p_i t_1 - p_i t_2)$$

$$R(\tau) = \sum_{i=1}^{n} \sigma_i^2 \cos p_i \tau$$

Since the conditions (1) and (2) for WSS are satisfied.

Hence, $\{X(t)\}$ is a WSS Process.

7. Let $X(t) = B\sin(100t + \theta)$, where B and θ are independent RV' s such that θ is uniform distributed over $(-\pi, \pi)$ and B has mean '0' and variance

'1'. Find mean and auto correlation function of $\{X(t)\}$

Solution:

Given $X(t) = B\sin(100t + \theta)$, where B and θ are independent RV' s.

 θ is uniform distributed over $(-\pi, \pi)$.

$$f(\theta) = \frac{1}{2\pi}, -\pi < \theta < \pi$$

Mean of $B = 0 \Rightarrow E[B] = 0$

variance of $B = 1 \Rightarrow E[B^2] = 1$

The mean of X(t) is given by

$$E[X(t)] = E[B\sin(100t + \theta)]$$

 $= E[B]E[\sin(100t + \theta)$

 $= 0 \times E[\sin(100t + \theta)]$

E[X(t)] = 0

Mean of X(t) = 0

The ACF of $\{X(t)\}$ is given by

$$\begin{aligned} R_{XX}(t_1, t_2) &= E[X(t_1)X(t_2)] \\ &= E[B\sin(100t_1 + \theta)B\sin(100t_2 + \theta)] \\ &= E[B^2\sin(100t_1 + \theta)\sin(100t_2 + \theta)] \\ &= E[B^2]E[\sin(100t_1 + \theta)\sin(100t_2 + \theta)] \\ &= 1 \times \frac{1}{2}E[\cos(100t_1 + \theta - 100t_2 - \theta) - \cos(100t_1 + \theta + 100t_2 + \theta)] \end{aligned}$$

$$= \frac{1}{2} \left[E[\cos(100t_1 - 100t_2) - \cos(100t_1 + 100t_2 + 2\theta)] \right]$$

$$= \frac{1}{2} \left[E(\cos 100\tau - \cos(100t_1 + 100t_2 + 2\theta)] \right]$$

$$= \frac{1}{2} \cos 100\tau - \frac{1}{2} E[\cos(100t_1 + 100t_2 + 2\theta)]$$

$$= \frac{1}{2} \cos 100\tau - \frac{1}{2} \int_{-\pi}^{\pi} \cos(100t_1 + 100t_2 + 2\theta)f(\theta) d\theta$$

$$= \frac{1}{2} \cos 100\tau - \frac{1}{2} \int_{-\pi}^{\pi} \cos(100t_1 + 100t_2 + 2\theta) \frac{1}{2\pi} d\theta$$

$$= \frac{1}{2} \cos 100\tau - \frac{1}{4\pi} \left[\frac{\sin(100t_1 + 100t_2 + 2\theta)}{2} \right]_{-\pi}^{\pi}$$

$$= \frac{1}{2} \cos 100\tau - \frac{1}{8\pi} [\sin(100t_1 + 100t_2 + 2\pi) - \sin(100t_1 + 100t_2 + 2\pi)]$$

$$= \frac{1}{2} \cos 100\tau - \frac{1}{8\pi} (0) = \frac{1}{2} \cos 100\tau$$

Auto Correlation function of $X(t) = \frac{1}{2}\cos 100\tau$

8. Let $X(t) = A\cos \lambda t + B\sin \lambda t$, where λ is a constant and A & B are independent RV 's with mean '0' & variance 1. Prove that $\{X(t)\}$ is covariance stationary.

Solution:

Given $X(t) = A\cos \lambda t + B\sin \lambda t$, where A&B are RV's and λ is a constant. Given E(A) = E(B) = 0.

Also given A and B are independent RV's.

 $\therefore E[AB] = E[A]E[B] = 0$

Also given Var(A) = Var(B) = 1

 $\Rightarrow E[A^2] = E[B^2] = 1$

To prove $\{X(t)\}$ is a covariance stationary process

(1) E[X(t)] is a constant

(2) $C_{XX}(t_1, t_2)$ is a function of τ NEEP

(1) $E[X(t)] = E[A\cos \lambda t + B\sin \lambda t]$

 $= E[A]\cos\lambda t + E[B]\sin\lambda t$

E[X(t)] = 0

 $\therefore E[X(t)]$ is a constant.

(2)
$$C_{XX}(t_1, t_2) = E[X(t_1)X(t_2)] - E[X(t_1)]E[X(t_2)]$$

 $= E[(A\cos\lambda t_1 + B\sin\lambda t_1)(A\cos\lambda t_2 + B\sin\lambda t_2)] - 0 \times 0$

 $= E[A^2 \cos \lambda t_1 \cos \lambda t_2 + AB \cos \lambda t_1 \sin \lambda t_2 +$

 $AB\sin\lambda t_1\cos\lambda t_2 + B^2\sin\lambda t_1\sin\lambda t_2]$

 $= E[A^{2}]\cos \lambda t_{1}\cos \lambda t_{2} + E[AB]\cos \lambda t_{1}\sin \lambda t_{2} + E[AB]\sin \lambda t_{1}\cos \lambda t_{2} +$

 $E[B^2]\sin\lambda t_1\sin\lambda t_2$

 $=\cos\lambda t_1\cos\lambda t_2 + 0 + 0 + \sin\lambda t_1\sin\lambda t_2$

 $= \cos \lambda (t_1 - t_2)$

$$C_{XX}(t_1, t_2) = \cos \lambda \tau$$

 $\therefore C_{XX}(t_1, t_2)$ is a function of τ

Since the conditions (1) and (2) for Covariance Stationary Process are $\{X(t)\}$ is a covariance stationary process.

Problems under SSS process:

For a SSS process, $E[X^n(t)]$ is a constant for every n.

1.Verify whether the sine wave $X(t) = Y \cos \omega t$, where Y is a random variable uniformly distributed over (0, 1) is a SSS process or not.

Solution:

Given, $X(t) = Y \cos \omega t$, where Y is a random variable uniformly distributed over (0,1)

 $f_Y(y) = 1; 0 < y < 1$

For a SSS process, $E[X^n(t)]$ is a constant for every n.

$$E[Y] = \int_0^1 y f_Y(y) \, dy$$

$$= \int_0^1 y \, dy = \left[\frac{y^2}{2}\right]_0^1 = \frac{1}{2}$$

 $E[X(t)] = E[Y \cos \omega t]$

 $= E[Y] \cos \omega t$

$$=\frac{1}{2}\cos\omega t$$

E[X(t)] is not a constant.

Hence $\{X(t)\}$ is not a SSS process.

2. Consider random process X((t) defined by X(t) = Ucost + Vsint, where U and V are independent random variables each of which assumes the values -2 and 1 with probabilities 1/3and 2/3 respectively. Show that {X(t)} is a wide sense stationary process and not a strict sense stationary process(SSS)

Solution:

Given X(t) = Ucost + Vsint where U and V are R.V'S with the following probability distributions

| u | -2 | 1 | "ALKULAM, KAN | Y _{COMP} | -2 | 1 |
|------|-----|-----|------------------|--------------------------|-----|-----|
| P(u) | 1/3 | 2/3 | OBSERVE OPTIMIZE | P(v) | 1/3 | 2/3 |

$$E(U) = \sum up(u) = \left(-2 \times \frac{1}{3}\right) + \left(1 \times \frac{2}{3}\right) = -\frac{2}{3} + \frac{2}{3} = 0$$
$$E(U^2) = \sum u^2 p(u) = \left(4 \times \frac{1}{3}\right) + \left(1 \times \frac{2}{3}\right) = \frac{4}{3} + \frac{2}{3} = 2$$
$$E(U^3) = \sum u^3 p(u) = \left(-8 \times \frac{1}{3}\right) + \left(1 \times \frac{2}{3}\right) = -\frac{8}{3} + \frac{2}{3} = -2$$

Similarly $E(V) = 0, E(V^2) = 2, E(V^3) = -2$

Since U and V are independent R.V'S, follow that

$$E(UV) = E(U)E(V) = 0 \times 0 = 0$$
$$E(U^{2}V) = E(U^{2})E(V) = 2 \times 0 = 0$$
$$E(UV^{2}) = E(U)E(V^{2}) = 0 \times 2 = 0$$

To Prove X(t) is WSS.

(i)Mean = E[X(t)] = constant

(ii) Auto correlation $R_{XX}(\tau) = E[X(t_1)X(t_2)]$ depends on τ

 $(i)E[X(t)] = E[U\cos t + V\sin t]$

 $= E[U]\cos t + E[V]\sin t$

$$= 0 + 0 = 0$$

E[X(t)] is a constant.

(ii)
$$R_{XX}(t_1, t_2) = E[X(t_1)X(t_2)]$$

$$= E[(U\cos t_1 + V\sin t_1)(U\cos t_2 + V\sin t_2)]$$

 $= E[U^2 \cos t_1 \cos t_2 + UV \cos t_1 \sin t_2 + UV \sin t_1 \cos t_2 + V^2 \sin t_1 \sin t_2]$

$$= E[U^{2} \cos t_{1} \cos t_{2}] + E[UV \cos t_{1} \sin t_{2}] + E[UV \sin t_{1} \cos t_{2}] + E[V^{2} \sin t_{1} \sin t_{2}]$$

 $= E[U^{2} \cos t_{1} \cos t_{2}] + E[V^{2} \sin t_{1} \sin t_{2}]$

 $= E[U^{2}] \cos t_{1} \cos t_{2} + E[V^{2}] \sin t_{1} \sin t_{2}$

$$= 2\cos t_1 \cos t_2 + 2\sin t_1 \sin t_2$$

$$= 2[\cos t_1 \cos t_2 + \sin t_1 \sin t_2]$$

 $= 2[\cos(t_1 - t_2)]$

 $\cos(-\theta) = \cos\theta$

 $\cos A \cos B + \sin A \sin B = \cos(A - B)$

 $= 2[\cos \tau]$

Since the conditions (1) and (2) for WSS are satisfied, X(t) is WSS process.

To check {X(t)} is Strict Sense Stationary

$$E[X^{3}(t)] = E[(U\cos t + V\sin t)^{3}]$$

$$= E(U^3\cos^3t + 3U^2V\cos^2t\sin t + 3UV^2\cos t\sin^2t + V^3\sin^3t)$$

$$= E(U^3)\cos^3 t + 3E(U^2V)\cos^2 t \sin t + 3E(UV^2)\cos t \sin^2 t + E(V^3)\sin^3 t$$

$$= -2\cos^3 t + 0 + 0 - 2\sin^3 t = -2(\cos^3 t + \sin^3 t)$$

Which depends on t.

Hence $\{X(t)\}$ is not a strict sense stationary process.

Cross Correlation Function:

Let {X(t)} and {Y(t)} be two random processes. Then cross correlation function of X(t) and Y(t) is $R_{XY}(t_1, t_2) = E[X(t_1)Y(t_2)]$

Jointly WSS Process:

Let $\{X(t)\}$ and $\{Y(t)\}$ be two random processes. Then the function of

X(t) and Y(t) is said to be JWSS process if

(i)E[X(t)] = constant

(ii)E[Y(t)] = constant

(iii) $R_{XY}(t_1, t_2)$ is a function of τ

Problems under Joint Wide Sense Stationary:

1.If $X(t) = 5\cos(10t + \theta)$ and $Y(t) = 20\sin(10t + \theta)$, where θ is uniformly distributed over $(0, 2\pi)$. Prove $\{X(t)\}$ and $\{Y(t)\}$ are JWSS.

Solution:

Given $(t) = 5\cos(10t + \theta)$, $Y(t) = 20\sin(10t + \theta)$, where θ is a RV uniform distributed over $(0, 2\pi)$

$$f(\theta) = \frac{1}{2\pi}$$
, $0 < \theta < 2\pi$

To prove $\{X(t)\}$ and $\{Y(t)\}$ is a JWSS process.

(i)E[X(t)] = constant

(ii)E[Y(t)] = constant

(iii)
$$R_{XY}(t, t + \tau)$$
 is a function of τ
(i) $E[X(t)] = E[5\cos(10t + \theta)]$
 $= 5 E[\cos(10t + \theta)]$
 $= 5 \int_{0}^{2\pi} \cos(10t + \theta) \frac{1}{2\pi} d\theta$
 $= \frac{5}{2\pi} \int_{0}^{2\pi} \cos(10t + \theta) d\theta$
 $= \frac{5}{2\pi} [\sin(10t + 2\pi) - \sin(10t)]$
 $= \frac{5}{2\pi} [\sin 10t - \sin 10t] = 0$
 $E[X(t)] = 0$ is a constant
(ii) $E[Y(t)] = E[20\sin(10t + \theta)]$
 $= 20 E[\sin(10t + \theta)]$
 $= 20 \int_{0}^{2\pi} \sin(10t + \theta) \frac{1}{2\pi} d\theta$
 $= \frac{20}{2\pi} \int_{0}^{2\pi} \sin(10t + \theta) d\theta$
 $= \frac{10}{\pi} [-\cos(10t + \theta)]_{0}^{2\pi}$

$$=\frac{10}{\pi}\left[-\cos(10t+2\pi)+\cos(10t)\right]$$

$$=\frac{10}{\pi}[-\cos 10t + \cos 10t] = 0$$

E[Y(t)] = 0 is a constant

(iii)
$$R_{XY}(\tau) = E[X(t)Y(t+\tau)]$$

$$= E[5\cos(10t+\theta)20\sin(10(t+\tau)+\theta)]$$

$$= E[5\cos(10t+\theta)20\sin(10t+10\tau+\theta)]$$

$$= \frac{100}{2}E[\sin(10t+\theta+10t+10\tau+\theta)-\sin(10t+\theta-10t-10\tau-\theta)]$$

$$= 50E[\sin(20t+10\tau+2\theta)-\sin(-10\tau)]$$

$$= 50E[\sin(20t+10\tau+2\theta)+\sin(10\tau)]$$

$$= 50\sin 10\tau + \frac{50}{2\pi}\int_{0}^{2\pi}\sin(20t+10\tau+2\theta)d\theta$$

$$= 50\sin 10\tau + \frac{25}{\pi}\left[-\frac{\cos(20t+10\tau+2\theta)}{2}\right]_{0}^{2\pi}$$

$$= 50\sin 10\tau + \frac{25}{2\pi}\left[-\cos(20t+10\tau+4\pi) + \cos(20t+10\tau)\right]$$

$$= 50\sin 10\tau + \frac{25}{2\pi}\left[-\cos(20t+10\tau) + \cos(20t+10\tau)\right]$$

$$= 50\sin 10\tau + \frac{25}{2\pi}\left[-\cos(20t+10\tau) + \cos(20t+10\tau)\right]$$

 $R_{XX}(t,t+ au$) is a function of au

Since the conditions (i), (ii) and (iii) for JWSS are satisfied, $\{X(t)\}$ and $\{Y(t)\}$ are JWSS processes.

2. Two random processes are obtained by $X(t) = A \cos \omega_0 t + B \sin \omega_0 t$ and $Y(t) = B \cos \omega_0 t - A \sin \omega_0 t$. Show that X(t) and Y(t) are JWSS if A and B are uncorrelated random variables with zero mean and same variances and ω_0 is a constant.

Solution:

Given $X(t) = A \cos \omega_0 t + B \sin \omega_0 t$ and $Y(t) = B \cos \omega_0 t - A \sin \omega_0 t$

Where A and B are random variables with mean zero.

 $\therefore E(A) = E(B) = 0....(1)$

Also given A and B have same variances

$$(i.e) Var(A) = Var(B)$$

$$\therefore E(A^2) = E(B^2) = 0....(2)$$

Also given A and B are uncorrelated

E(AB) = E(A) E(B) = 0....(3)

To Prove {X(t)} and {Y(t)} is a JWSS process.

(i)
$$E[X(t)] = constant$$

(ii) $E[Y(t)] = constant$

$$\begin{aligned} (\text{iii})R_{XY}(t_1, t_2) \text{ is a function of } \tau \\ (\text{i}) E[X(t)] &= E[A \cos \omega_0 t + B \sin \omega_0 t] \\ &= E[A] \cos \omega_0 t + E[B] \sin \omega_0 t] \\ &= 0 \text{ (by 1)} \\ E[X(t)] &= 0 \text{ is a constant} \\ (\text{ii}) E[Y(t)] &= E[B \cos \omega_0 t - A \sin \omega_0 t] \\ &= E[B] \cos \omega_0 t - E[A] \sin \omega_0 t] \\ &= 0 \text{ (by 1)} \\ E[Y(t)] &= 0 \text{ is a constant} \\ (\text{iii}) R_{XY}(t_1, t_2) &= E[X(t_1)Y(t_2)] \\ &= E[AB \cos \omega_0 t_1 \cos \omega_0 t_2 - A^2 \cos \omega_0 t_1 \sin \omega_0 t_2 + B^2 \sin \omega_0 t_1 \cos \omega_0 t_2 - AB \sin \omega_0 t_1 \cos \omega_0 t_2 - E[A^2] \cos \omega_0 t_1 \sin \omega_0 t_2 + E[B^2] \sin \omega_0 t_1 \cos \omega_0 t_2 - E[A^2] \cos \omega_0 t_1 \sin \omega_0 t_2 + E[B^2] \sin \omega_0 t_1 \cos \omega_0 t_2 - E[A^2] \cos \omega_0 t_1 \sin \omega_0 t_2 + E[B^2] \sin \omega_0 t_1 \cos \omega_0 t_2 - 0 \\ &= -E[A^2] \cos \omega_0 t_1 \sin \omega_0 t_2 + E[B^2] \sin \omega_0 t_1 \cos \omega_0 t_2 - 0 \\ &= -E[A^2] (\sin \omega_0 t_1 \cos \omega_0 t_2 - \cos \omega_0 t_1 \sin \omega_0 t_2) \\ &= E[A^2] (\sin \omega_0 t_1 \cos \omega_0 t_2 - \cos \omega_0 t_1 \sin \omega_0 t_2) \\ &= E[A^2] (\sin \omega_0 t_1 \cos \omega_0 t_2 - \cos \omega_0 t_1 \sin \omega_0 t_2) \\ &= E[A^2] (\sin \omega_0 t_1 \cos \omega_0 t_2 - \cos \omega_0 t_1 \sin \omega_0 t_2) \\ &= E[A^2] \sin \omega_0 (t_1 - t_2) \end{aligned}$$

 $= E[A^2]sin\omega_0\tau$, which is a function of τ

 $\therefore R_{XY}(t_1, t_2)$ is a function of τ

 $\sin A \cos B - \cos A \sin B = \sin(A - B)$

Since the conditions (1), (2) and (3) for JWSS are satisfied, X(t) and Y(t) are

is JWSS process.

Problems under Ergodic Process:

1. Let X(t) = A, where A is a random variable. Prove that $\{X(t)\}$ is not

a mean ergodic.

Solution:

Given X(t) = A, where A is a random variable

To Prove $\{X(t)\}$ is a mean ergodic, we have to prove

$$E[X(t)] = \lim_{T \to \infty} \overline{X_T}$$

The ensemble mean of $\{X(t)\}$ is given by,

E[X(t)] = E[A] - - - - - - (1)

The time average is given by,

$$\overline{X_T} = \frac{1}{2T} \int_{-T}^{T} X(t) dt = \frac{1}{2T} \int_{-T}^{T} A dt$$
$$= \frac{A}{2T} \int_{-T}^{T} dt = \frac{A}{2T} [t]_{-T}^{T} = \frac{A}{2T} (2T) = A$$

$$\lim_{T \to \infty} \overline{X_T} = A - - - -(2)$$

From (1) and (2)

$$E[X(t)] \neq \lim_{T \to \infty} \overline{X_T}$$

 \therefore {*X*(*t*)} is not mean Ergodic.

2. A random process has sample functions of the form $X(t) = A \cos(\omega t + \theta)$, where ω is constant and A is a random variable with mean zero and variance one and θ is also a random variable that is uniformly distributed between 0 and 2π . Assume that the random variables A and θ are independent. Prove that X(t) is a mean ergodic process?

Solution:

Given $X(t) = A \cos(\omega t + \theta)$, where A is a random variable with mean zero.

$$\therefore E(A) = 0, E(A^2) = 1$$

 θ is uniformly distributed between 0 and 2π

$$f(\theta) = \frac{1}{2\pi}; 0 < \theta < 2\pi$$

To Prove {X(t)} is Mean Ergodic.

we have to prove

$$E[X(t)] = \lim_{T \to \infty} \overline{X_T}$$

The ensemble mean of $\{X(t)\}$ is given by,

 $E[X(t)] = E[A\cos(\omega t + \theta)]$ GINEER

= $E[A] \cos(\omega t + \theta)$ since A and θ are independent R.V'S

= 0 (1)

The time average is given by,

$$\overline{X_T} = \frac{1}{2T} \int_{-T}^{T} X(t) dt$$

$$= \frac{1}{2T} \int_{-T}^{T} A \cos(\omega t + \theta) dt$$

$$= \frac{A}{2T} \int_{-T}^{T} \cos(\omega t + \theta) dt$$

$$= \frac{A}{2T} \left[\frac{\sin(\omega t + \theta)}{\omega} \right]_{-T}^{T}$$

$$\overline{X_T} = \frac{A}{2T\omega} \left[\sin(\omega T + \theta) - \sin(-\omega T + \theta) \right]$$

$$\lim_{T \to \infty} \overline{X_T} = \lim_{T \to \infty} \frac{A}{2T\omega} \left[\sin(\omega T + \theta) - \sin(-\omega T + \theta) \right]$$

$$= 0......(2)$$

From (1)and (2) , $E[X(t)] = \lim_{T \to \infty} \overline{X_T}$

 \therefore {*X*(*t*)} is a mean Ergodic Process.

Correlation Ergodic Process:

Let {X(t)} be a random process. The ensemble auto correlation function is $R_{XX}(t_1, t_2) = E[X(t_1)X(t_2)]$

The time auto correlation function is $\overline{X_T} = \frac{1}{2T} \int_{-T}^{T} X(t) X(t + \tau) dt$

A process {X(t)} is said to be correlation ergodic if $R_{XX}(t_1, t_2) = \lim_{T \to \infty} \overline{X_T}$

Problems under Correlation Ergodic Process:

1. Given a WSS random process $\{X(t)\} = 10\cos(100t + \theta)$, where θ is

uniformly distributed over $(-\pi, \pi)$. Prove that X(t) is a correlation

ergodic.

Solution:

Given $\{X(t)\} = 10\cos(100t + \theta)$

$$\Rightarrow f(\theta) = \frac{1}{2\pi}, -\pi < \theta < \pi$$

 $R_{XX}(t,t+\tau) = E[X(t)X(t+\tau)]$

$$= E[10\cos(100t + \theta) \ 10\cos(100(t + \tau) + \theta)]$$

$$= \frac{100}{2}E[\cos(100t + \theta) \cos(100t + 100\tau + \theta)]$$

$$= 50 \ E[\cos(100t + \theta + 100t + 100\tau + \theta) + \cos(100t + \theta - 100t - 100\tau - \theta)]$$

$$= 50 \ E[\cos(200t + 2\theta + 100\tau) + \cos(-100\tau)]$$

$$= 50 \ E[\cos(200t + 2\theta + 100\tau) + \cos(100\tau)]$$

$$= 50 \ \cos(100\tau) + \frac{50}{2\pi} \int_{0}^{2\pi} \cos(200t + 100\tau + 2\theta) d\theta$$

$$= 50 \ \cos(100\tau) + \frac{25}{2\pi} \left[\frac{\sin(200t + 100\tau + 2\theta)}{2} \right]_{0}^{2\pi}$$

$$= 50 \ \cos(100\tau) + \frac{25}{2\pi} \left[\sin(200t + 100\tau + 4\pi) - \sin(200t + 100\tau - 0) \right]$$

$$= 50 \ \cos(100\tau + \frac{25}{2\pi} \left[\sin(200t + 100\tau) - \sin(200t + 100\tau) \right]$$

$$R_{XX}(t, t + \tau) = 50 \ \cos(100\tau)$$
Let $\overline{X_T} = \frac{1}{2\tau} \int_{-\tau}^{T} X(t) \ X(t + \tau) dt$

$$= \frac{1}{2\tau} \left[\int_{-\tau}^{T} 50 \cos(100\tau) dt + 50 \ \int_{-\tau}^{T} \cos(200t + 100\tau + 2\theta) dt \right]$$

$$= \frac{1}{2\tau} \left\{ [50 \cos(100\tau) t]_{-\tau}^{T} + 50 \left[\frac{\sin(200t + 100\tau + 2\theta)}{200} \right]_{\tau}^{T} \right\}$$

$$\begin{split} &= \frac{1}{2T} \left\{ [50\cos(100\tau) (T - (-T)] + \frac{50}{200} [\sin(200t + 100\tau + 2\theta) - \\ \sin(200(-T) + 100\tau + 2\theta)] \right\} \\ &= \frac{1}{2T} \left\{ [50\cos(100\tau) (2T)] \\ &+ \frac{1}{4} [\sin(200t + 100\tau + 2\theta) - \sin(-200T + 100\tau + 2\theta)] \right\} \\ &\lim_{T \to \infty} \overline{X_T} = \lim_{T \to \infty} \frac{1}{2T} \left\{ [50\cos(100\tau) (2T)] \\ &+ \frac{1}{4} [\sin(200t + 100\tau + 2\theta) - \sin(-200T + 100\tau + 2\theta)] \right\} \\ &= \lim_{T \to \infty} \frac{1}{2T} 50\cos(100\tau) (2T) + \lim_{T \to \infty} \frac{1}{8T} [\sin(200t + 100\tau + 2\theta)] \\ &- \sin(-200T + 100\tau + 2\theta)] \\ &= \lim_{T \to \infty} 50\cos(100\tau) + \lim_{T \to \infty} \frac{1}{8T} [\sin(200t + 100\tau + 2\theta)] \\ &= 50\cos(100\tau) + 0 \\ &= 50\cos(100\tau) \\ R_{XX}(t, t + \tau) = \lim_{T \to \infty} \overline{X_T} \end{split}$$

Hence X(t) is a correlation ergodic.

2. Find the ACF of the periodic time function $X(t) = A \sin \omega t$.

Solution:

Since periodic time function X(t) is given, we use time auto correlation function.

The ACF of the process is given by $R_{XX}(t_1, t_2) = \lim_{T \to \infty} \overline{X_T}$



$$= \frac{A^2}{4T} \left[\cos\omega\tau(2T) - \frac{\sin(2\omega T + \omega\tau)}{2\omega} + \frac{\sin(-2\omega T + \omega\tau)}{2\omega} \right]$$
$$= \frac{A^2}{4T} \cos\omega\tau(2T) + \frac{A^2}{4T} \left[-\frac{\sin(2\omega T + \omega\tau)}{2\omega} + \frac{\sin(-2\omega T + \omega\tau)}{2\omega} \right]$$

The ACF of the process is given by

$$R_{XX}(t_1, t_2) = \lim_{T \to \infty} \overline{X_T}$$

$$= \frac{A^2}{2} \cos \omega \tau + \lim_{T \to \infty} \frac{A^2}{4T} \left[-\frac{\sin(2\omega T + \omega \tau)}{2\omega} + \frac{\sin(-2\omega T + \omega \tau)}{2\omega} \right]$$

$$R_{XX}(t_1, t_2) = \frac{A^2}{2} \cos \omega \tau$$

$$R_{XX}(t_1, t_2) = \frac{A^2}{2} \cos \omega \tau$$