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| NAME OF THE SUBJECT: ENGINEERING MECHANICS |  |
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| SUBJECT CODE | : ME3351 |
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UNIT V: FRICTION

## WEDGE FRICTION



A wedge is a piece of wood or metal, usually of a triangular (or) trapezoidal shape in cross section used for Lifting Loads (or) for slight adjustment like tightening keys for shift

When the force P is applied, sliding take place on the edge AC, DG, and Gf. Hence the reactive force components, normal reactions and the frictional forces are also developed on these sliding surface

Now Let as see the direction of these reactive forces, and draw the free body diagram of wedge and body.

Equilibrium of wedge


Normal force and Frictional force are combined to a single resultant force ' $R_{F}$ ' $R_{F 1} \& R_{F 2}$ are drawn on wedge

Where $R_{F 1}=\sqrt{F_{1}{ }^{2}+R_{1}{ }^{2}}$

$$
R_{F 2}=\sqrt{F_{2}{ }^{2}+R_{2}{ }^{2}}
$$

$F_{1} \& F_{2}$ are Limiting friction $\emptyset_{1}, \emptyset_{2}$ means of angle of friction
It is defined as the in $\mathrm{b} / \mathrm{w}$ the angle of [Line of action of the normal reaction $N_{1} \& N_{2}$ ] and Resultant force $R_{F_{1}} \& R_{F_{2}}$


Equilibrium of body

When the force ' P ' push the wedge, the body tends to move upwards, hence the frictional force $F_{3}$ on the surface AD is acting download.

Then the normal reaction $R_{3}$ and $F_{3}$ are replaced by a single resultant $R_{F 3}$, which makes on angle of $\emptyset_{3}$ with line of action of normal reaction $R_{3}$

Concurrent forces $R_{1} R_{2}$, self weight(w)
Note (i) always draw the free body diagram of wedge first then draw the force body diagram of the below
(ii) while solving, if the Load is given, solve free body of block first and if the force ' P ' is given.solve the free body of wedge
(iii) self-weight of the wedge is neglected

## Problem: 1

Determine the horizontal force P required to raise the 200 kg block the efficient of friction for all the contact surface is 0.25


Free body Diagram of block


Sum of all X direction force

$$
\begin{aligned}
& \sum F_{X}=0+\longleftarrow- \\
& R_{1}-R_{2} \cos 78-F_{2} \cos 12^{\circ}=0 \\
& R_{1}-0.207 R_{2}-\mu R_{2} \cos 12^{\circ}=0 \\
& R_{1}-0.207 R_{2}-0.25 \times R_{2} \times \cos 12^{\circ}=0 \\
& R_{1}-0.207 R_{2}-0.24 R_{2}=0 \\
& R_{1}=0.207 R_{2}+0.24 R_{2} \\
& R_{1}=0.45 R_{2}
\end{aligned}
$$

Sum of all Y direction force

$$
\begin{aligned}
& \sum F_{Y}=0 \quad \uparrow+ \\
& -1962-F_{1}-F_{2} \sin 12+R_{2} \sin 78=0 \\
& -1962-0.25 R_{1}-0.25 R_{2} \sin 12^{\circ}+R_{2} \sin 78^{\circ}=0 \\
& -1962-0.25 R_{1}-0.051 R_{2}+0.97 R_{2}=0 \\
& -1962-0.25 \times\left[0.45 R_{2}\right]-0.051 R_{2}+0.97 R_{2}=0 \\
& -1962-0.112 R_{2}-0.051 R_{2}+0.97 R_{2}=0 \\
& -1962+0.807 R_{2}=0 \\
& 0.807 R_{2}=1962 \\
& R_{2}=\frac{1962}{0.867} \\
& R_{2}=2431.22 \mathrm{~N} \\
& R_{2} \text { Value sub in eqn }(1) \\
& R_{1}=0.45 R_{2}----0.45 \times 2431.22 \\
& R_{1}=1094 \mathrm{~N} \\
& F_{1}=\mu R_{1}=0.25 \times 1094=273.51 \mathrm{~N} \\
& F_{2}=\mu R_{2}=0.25 \times 2431=607.75 \mathrm{~N}
\end{aligned}
$$

Free body diagram of wedge


$$
\begin{aligned}
& \sum F_{X}=0 \\
& -P+F_{3}+2431.22 \cos 78^{\circ}+607.75 \cos 12^{\circ}=0 \\
& -P+\mu R_{3}+278+594.46=0 \\
& -P=-\mu R_{3}-2378-594.46 \\
& -P=-\left[\mu R_{3}+2378+594.46\right] \\
& P=0.25 \times R_{3}+2378+594.46 \text {-------------- (2) } \\
& \sum F_{Y}=0 \\
& R_{3}-R_{2} \sin 78^{\circ}+607.75 \sin 12^{\circ}=0 \\
& R_{3}-2431.51 \sin 78^{\circ}+607.75 \sin 12^{\circ}=0 \\
& R_{3}-505.47+126.35=0 \\
& R_{3}=505.47-126.35 \\
& R_{3}=379.11 \mathrm{~N}
\end{aligned}
$$

$R_{3}$ vlaue sub in Eqn (2)
$P=0.25 \times R_{3}+2378+594.46$
$P=0.25 \times 379.11+2378+594.46$
$P=3067.23 N$

