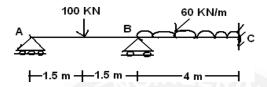
4.3. ANALYSIS THE CONTINUOUS BEAM BY FLEXIBILITY METHOD.

4.3.1. NUMERICAL PROBLEMS ON CONTINUOUS BEAMS;

PROBLEM NO:01

Analysis the continuous beam shown in fig, by using Flexibility method.



Solution:

• Static indeterminacy:

Degree of redundancy = (1 + 1 + 3) - 3 = 2

Release at B and C by apply hinge

• Fixed End Moments:

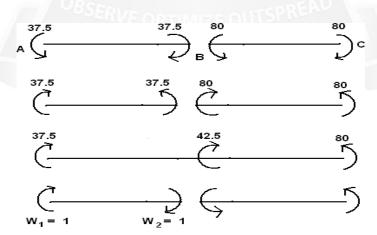
$$MFAB = -W1/8 = -100X3/8 = -37.5 \text{ kNm}$$

$$MFBA = W1/8 = 100X3/8 = 37.5 \text{ kNm}$$

$$MFBC = -W1^2/12 = -60x4^2/12 = -80 \text{ kNm}$$

$$MFCB = Wl^2/12 = 60x4^2/12 = 80 \text{ kNm}$$

• Equivalent Joint Loads:



• Flexibility Co-efficient Matrix (B):

$$B = Bw \cdot Bx$$

$$\mathbf{B}_{\mathrm{W}} \ = \left[\begin{array}{cc} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{array} \right] \quad \text{ and } \mathbf{B}_{\mathrm{X}} \quad = \left[\begin{array}{cc} 0 & 0 \\ -1 & 0 \\ 1 & 0 \\ 0 & 1 \end{array} \right]$$

$$\mathbf{B} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

• Flexibility Matrix (F):

$$F = \frac{L}{6EI} \begin{bmatrix} 2 & -1 & 0 & 0 \\ -1 & 2 & 0 & 0 \\ 0 & 0 & 2 & -1 \\ 0 & 0 & -1 & 2 \end{bmatrix}$$

$$F = \frac{1}{EI} \begin{bmatrix} 1 & -0.5 & 0 & 0 \\ -0.5 & 1 & 0 & 0 \\ 0 & 0 & 1.33 & -0.67 \\ 0 & 0 & -0.67 & 1.33 \end{bmatrix}$$

$$\mathbf{F}_{\mathbf{X}} = \mathbf{B}_{\mathbf{X}}^{\mathbf{T}} \cdot \mathbf{F} \cdot \mathbf{B}_{\mathbf{X}}$$

$$= \frac{1}{\text{EI}} \begin{bmatrix} 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & -0.5 & 0 & 0 \\ -0.5 & 1 & 0 & 0 \\ 0 & 0 & 1.33 & -0.67 \\ 0 & 0 & -0.67 & 1.33 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ -1 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$F_x = \frac{1}{EI} \begin{bmatrix} 2.33 & -0.67 \\ -0.67 & 1.33 \end{bmatrix}$$

$$E_{x}^{-1} = EI \begin{bmatrix} 0.502 & 0.253 \\ 0.253 & 0.879 \end{bmatrix}$$

$$\mathbf{F}\mathbf{w} = \mathbf{B}\mathbf{x}^{\mathrm{T}} \cdot \mathbf{F} \cdot \mathbf{B}\mathbf{w}$$

$$= \frac{1}{\text{EI}} \begin{bmatrix} 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & -0.5 & 0 & 0 \\ -0.5 & 1 & 0 & 0 \\ 0 & 0 & 1.33 & -0.67 \\ 0 & 0 & -0.67 & 1.33 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$F_{W} = \frac{1}{EI} \begin{bmatrix} 0.5 & -1 \\ 0 & 0 \end{bmatrix}$$

• Displacement Matrix (X):

$$X = -F_{X}^{-1} \cdot F_{W} \cdot W$$

$$= -\frac{EI}{EI} \begin{bmatrix} 0.502 & 0.253 \\ 0.253 & 0.879 \end{bmatrix} \begin{bmatrix} 0.5 & -1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 37.5 \\ 42.5 \end{bmatrix}$$

$$= -\begin{bmatrix} 0.251 & -0.502 \\ 0.127 & -0.253 \end{bmatrix} \begin{bmatrix} 37.5 \\ 42.5 \end{bmatrix}$$

$$= -\begin{bmatrix} -11.923 \\ -5.99 \end{bmatrix}$$

$$X = \begin{bmatrix} 11.923 \\ 5.99 \end{bmatrix}$$

• Internal Force (P):

$$\mathbf{P} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 37.5 \\ 42.5 \\ 11.923 \\ 5.99 \end{bmatrix}$$

$$P = \begin{bmatrix} 37.5 \\ 30.58 \\ 11.923 \\ 5.99 \end{bmatrix}$$

• Final Moments (M):

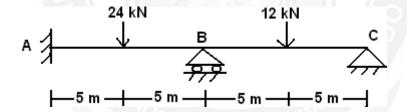
$$\mathbf{M} = \mathbf{\mu} + \mathbf{P}$$

$$= \begin{bmatrix} -37.5 \\ 37.5 \\ -80 \\ 80 \end{bmatrix} + \begin{bmatrix} 37.5 \\ 30.58 \\ 11.923 \\ 5.99 \end{bmatrix}$$

$$\mathbf{M} = \begin{bmatrix} 0 \\ 68.08 \\ -68.08 \\ 95.99 \end{bmatrix}$$

PROBLEM NO:02

Analysis the continuous beam ABC shown in fig,by using Flexibility method. And sketch the bending moment diagram.



Solution:

• Static indeterminacy:

Degree of redundancy =
$$(3 + 1 + 1) - 3 = 2$$

Release at A and B by apply hinge

• Fixed End Moments:

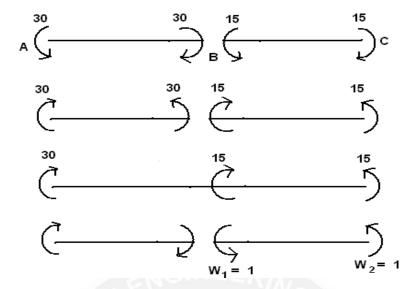
$$MFAB = -W1/8 = -24X10/8 = -30 \text{ kNm}$$

$$MFBA = W1/8 = 24X10/8 /8 = 30 \text{ kNm}$$

$$MFAB = -W1/8 = -12X10/8 = -15 \text{ kNm}$$

$$MFBA = Wl/8 = 12X10/8 /8 = 15 kNm$$

• Equivalent Joint Loads:



• Flexibility Co-efficient Matrix (B):

$$\mathbf{B} = \mathbf{B}_{\mathbf{W}} \cdot \mathbf{B}_{\mathbf{X}}$$

$$\mathbf{B} = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \\ 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

• Flexibility Matrix (F):

$$F = \frac{L}{6EI} \begin{bmatrix} 2 & -1 & 0 & 0 \\ -1 & 2 & 0 & 0 \\ 0 & 0 & 2 & -1 \\ 0 & 0 & -1 & 2 \end{bmatrix}$$

$$F = \frac{1}{EI} \begin{bmatrix} 3.33 & -1.67 & 0 & 0 \\ -1.67 & 3.33 & 0 & 0 \\ 0 & 0 & 3.33 & -1.67 \\ 0 & 0 & -1.67 & 3.33 \end{bmatrix}$$

$$\mathbf{F}_{\mathbf{X}} = \mathbf{B}_{\mathbf{X}}^{\mathbf{T}} \cdot \mathbf{F} \cdot \mathbf{B}_{\mathbf{X}}$$

$$= \frac{1}{\text{EI}} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 1 & 0 \end{bmatrix} \begin{bmatrix} 3.33 & -1.67 & 0 & 0 \\ -1.67 & 3.33 & 0 & 0 \\ 0 & 0 & 3.33 & -1.67 \\ 0 & 0 & -1.67 & 3.33 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$$

$$F_{x} = \frac{1}{EI} \begin{bmatrix} 3.33 & 1.67 \\ 1.67 & 6.66 \end{bmatrix}$$

$$F_x^{-1} = EI \begin{bmatrix} 0.3435 & -0.086 \\ -0.086 & 0.1717 \end{bmatrix}$$

 $\mathbf{F}\mathbf{w} = \mathbf{B}\mathbf{x}^{\mathrm{T}} \cdot \mathbf{F} \cdot \mathbf{B}\mathbf{w}$

$$= \frac{1}{\text{EI}} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 1 & 0 \end{bmatrix} \begin{bmatrix} 3.33 & -1.67 & 0 & 0 \\ -1.67 & 3.33 & 0 & 0 \\ 0 & 0 & 3.33 & -1.67 \\ 0 & 0 & -1.67 & 3.33 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$F_{W} = \frac{1}{EI} \begin{bmatrix} 0 & 0 \\ 3.33 & -1.67 \end{bmatrix}$$

• Displacement Matrix (X):

$$X = -F_{X}^{-1} \cdot F_{W} \cdot W$$

$$= -\frac{EI}{EI} \begin{bmatrix} 0.3435 & -0.086 \\ -0.086 & 0.1717 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 3.33 & -1.67 \end{bmatrix} \begin{bmatrix} -15 \\ -15 \end{bmatrix}$$

$$= -\begin{bmatrix} -0.286 & 0.144 \\ 0.144 & -0.286 \end{bmatrix} \begin{bmatrix} -15 \\ -15 \end{bmatrix}$$
$$= -\begin{bmatrix} 2.13 \\ -4.29 \end{bmatrix}$$
$$X = \begin{bmatrix} -2.13 \\ 4.29 \end{bmatrix}$$

• Internal Force (P):

$$P = []_X$$

$$= \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \\ 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} -15 \\ -15 \\ -2.13 \\ 4.29 \end{bmatrix}$$

$$P = \begin{bmatrix} -2.13 \\ -4.29 \\ -10.71 \\ -15 \end{bmatrix}$$

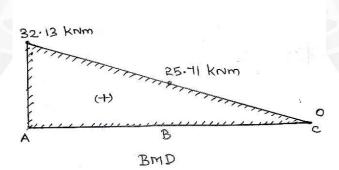
• Final Moments (M):

$$\mathbf{M} = \mathbf{\mu} + \mathbf{P}$$

$$= \begin{bmatrix} -30\\30\\-15\\15 \end{bmatrix} + \begin{bmatrix} -2.13\\-4.29\\-10.71\\-15 \end{bmatrix}$$

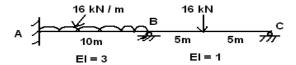
$$\mathbf{M} = \begin{bmatrix} -32.13 \\ 25.71 \\ -25.71 \\ 0 \end{bmatrix}$$

• Bending Moment Diagram:



PROBLEM NO:03

Analysis the continuous beam shown in fig,by using Flexibility method.



Solution:

• Static indeterminacy:

Degree of redundancy =
$$(3 + 1 + 1) - 3 = 2$$

Release at A and B by apply hinge

• Fixed End Moments:

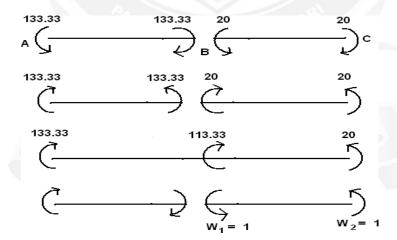
$$MFAB = -W1^2/12 = -16x10^2/12 = -133.33 \text{ kNm}$$

$$MFBA = Wl^2/12 = 16x10^2/12 = 133.33 \text{ kNm}$$

$$MFBC = -W1/8 = -16X10/8 = -20 \text{ kNm}$$

$$MFCB = W1/8 = 16X10/8 = 20 \text{ kNm}$$

• Equivalent Joint Loads:



• Flexibility Co-efficent Matrix (B):

$$\mathbf{B} = \mathbf{B}\mathbf{w} \cdot \mathbf{B}\mathbf{x}$$

$$\mathbf{B} = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \\ 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

• Flexibility Matrix (F):

$$F = \frac{L}{6EI} \begin{bmatrix} 2 & -1 & 0 & 0 \\ -1 & 2 & 0 & 0 \\ 0 & 0 & 2 & -1 \\ 0 & 0 & -1 & 2 \end{bmatrix}$$

$$F = \begin{bmatrix} 1.11 & -0.56 & 0 & 0 \\ -0.56 & 1.11 & 0 & 0 \\ 0 & 0 & 3.33 & -1.67 \\ 0 & 0 & -1.67 & 3.33 \end{bmatrix}$$

 $\mathbf{F}_{\mathbf{X}} = \mathbf{B}_{\mathbf{X}}^{\mathrm{T}} \cdot \mathbf{F} \cdot \mathbf{B}_{\mathbf{X}}$

$$= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1.11 & -0.56 & 0 & 0 \\ -0.56 & 1.11 & 0 & 0 \\ 0 & 0 & 3.33 & -1.67 \\ 0 & 0 & -1.67 & 3.33 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \\ 0 & 0 \end{bmatrix}$$

$$\mathbf{F_x} = \begin{bmatrix} 1.11 & 0.56 \\ 0.56 & 4.44 \end{bmatrix}$$

$$\mathbf{E}_{\mathbf{x}}^{-1} = \begin{bmatrix} 0.962 & -0.121 \\ -0.121 & 0.241 \end{bmatrix}$$

 $\mathbf{F}\mathbf{w} = \mathbf{B}\mathbf{x}^{\mathrm{T}} \cdot \mathbf{F} \cdot \mathbf{B}\mathbf{w}$

$$= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1.11 & -0.56 & 0 & 0 \\ -0.56 & 1.11 & 0 & 0 \\ 0 & 0 & 3.33 & -1.67 \\ 0 & 0 & -1.67 & 3.33 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$F_{W} = \begin{bmatrix} 0 & 0 \\ 3.33 & -1.67 \end{bmatrix}$$

• Displacement Matrix (X):

$$X = -F_{X}^{-1} \cdot F_{W} \cdot W$$

$$= -\begin{bmatrix} 0.962 & -0.121 \\ -0.121 & 0.241 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 3.33 & -1.67 \end{bmatrix} \begin{bmatrix} -113.33 \\ -20 \end{bmatrix}$$

$$= -\begin{bmatrix} 41.62 \\ -82.90 \end{bmatrix}$$

$$X = \begin{bmatrix} -41.62 \\ 82.90 \end{bmatrix}$$

• Internal Force (P):

$$P = []_X$$

$$= \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \\ 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} -113.33 \\ -20 \\ -41.62 \\ 82.90 \end{bmatrix}$$

$$P = \begin{bmatrix} -41.62 \\ -82.90 \\ -30.43 \\ -20 \end{bmatrix}$$

• Final Moments (M):

$$\mathbf{M} = \mathbf{\mu} + \mathbf{P}$$

$$= \begin{bmatrix} -133.33 \\ 133.33 \\ -20 \\ 20 \end{bmatrix} + \begin{bmatrix} -41.62 \\ -82.90 \\ -30.43 \\ -20 \end{bmatrix}$$

$$\mathbf{M} = \begin{bmatrix} -174.95 \\ 50.43 \\ -50.43 \\ 0 \end{bmatrix}$$

