BAYESIAN CLASSIFICATION

• *Probabilistic learning:* Calculate explicit probabilities for hypothesis, among the most practical approaches to certain types of learning problems

• *Incremental:* Each training example can incrementally increase/decrease the probability that a hypothesis is correct. Prior knowledge can be combined with observed data.

• Probabilistic prediction: Predict multiple hypotheses, weighted by their probabilities

• *Standard:* Even when Bayesian methods are computationally intractable, they can provide a standard of optimal decision making against which other methods can be measured

Given training data D, posteriori probability of a hypothesis h, P(h|D) follows the Bayes theorem

The formula for Bayes' theorem is



MAP (maximum posteriori) hypothesis

$$h_{map} = \arg \max_{h \in H} (P(h \mid D))$$
$$= \arg \max_{h \in H} \left(\frac{P(D \mid h)P(h)}{P(D)} \right)$$
$$= \arg \max_{h \in H} (P(D \mid h)P(h))$$

Practical difficulty: require initial knowledge of many probabilities, significant computational cost

Naïve Bayes Classifier (I)

- □ A simplified assumption: attributes are conditionally independent:
- □ Greatly reduces the computation cost, only count the class distribution.

Naive Bayesian Classifier (II)

Given a training set, we can compute the probabilities

BAYESIAN CLASSIFICATION Algorithm

The classification problem may be formalized using a-posteriori probabilities:

- P(C|X) = prob. that the sample tuple
- $X = \langle x1, \dots, xk \rangle$ is of class C.
- E.g. P(class=N | outlook=sunny, windy=true,...)
- \bullet Idea: assign to sample X the class label C such that P(C|X) is maximal

Estimating a-posteriori probabilities

Bayes theorem:

 $P(C|X) = P(X|C) \cdot P(C) / P(X)$

- P(X) is constant for all classes
- P(C) = relative freq of class C samples
- C such that P(C|X) is maximum = C such that $P(X|C) \cdot P(C)$ is maximum
- Problem: computing P(X|C) is unfeasible!

BAYESIAN BELIEF NETWORKS

- Bayesian belief network allows a subset of the variables conditionally independent
- A graphical model of causal relationships
 - Represents dependency among the variables
 - Gives a specification of joint probability distribution

The conditional probability table (CPT) for variable Lung Cancer:

	(FH, S)	(FH, ~\$)	(~FH, S)	(~FH, ~\$)
LC	0.8	0.5	0.7	0.1
~LC	0.2	0.5	0.3	0.9

CPT shows the conditional probability for each possible combination of its parents

Derivation of the probability of a particular combination of values of X, from CPT:

$$P(x_1, \dots, x_n) = \prod_{i=1}^{n} \frac{P(x_i \mid Parents(Y_i))}{\sum_{i=1}^{n} P(x_i \mid Parents(Y_i))}$$