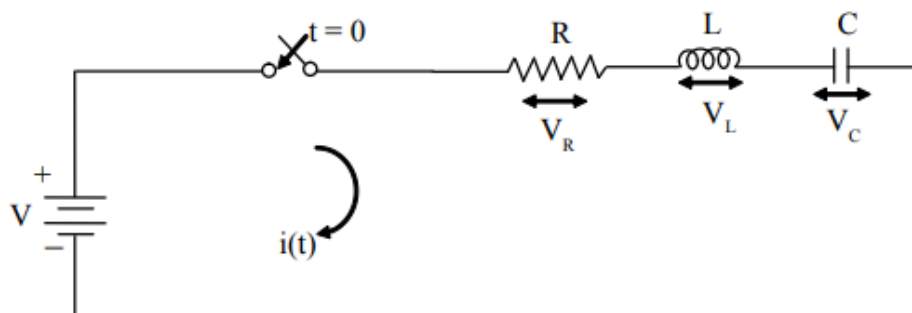


### DC Response of RLC Series Circuit :



*Fig. 4.10 RLC series circuit*

The RLC series circuit is shown above which is excited by a DC source. Assume that at  $t = 0$ , the switch S is closed. While closing the switch, the voltage drop across the capacitor and current flowing through the inductor is zero.

Applying KVL to the circuit,

$$V = V_R(t) + V_L(t) + V_C(t)$$

$$V = Ri(t) + L \frac{di(t)}{dt} + \frac{1}{C} \int i(t) dt \quad \text{-----(13)}$$

By applying laplace transform to equation (13), we get

$$\frac{V}{S} = RI(s) + L[SI(s) - I(0)] + \frac{1}{C} \left[ \frac{I(s)}{S} + \frac{q(0)}{S} \right]$$

Assume  $I(0) = q(0) = 0$

$$\therefore \frac{V}{S} = RI(S) + LSI(S) + \frac{I(S)}{CS}$$

$$= I(S) \left[ R + LS + \frac{1}{CS} \right]$$

$$\frac{V}{S} = I(S) \left[ \frac{RCS + LS^2C + 1}{CS} \right] = I(S) \left[ \frac{S^2LC + RCS + 1}{CS} \right]$$

$$V = I(S) \left[ \frac{S^2LC + SRC + 1}{C} \right]$$

$$V = I(S) \frac{LC}{C} \left[ S^2 + \frac{SR}{L} + 1/LC \right]$$

$$\therefore I(S) = \frac{V}{L \left[ S^2 + \frac{R}{L}S + 1/LC \right]} \text{-----(14)}$$

The roots of the denominator for equation (14)

$$\begin{aligned} S_1, S_2 &= \frac{-R/L \pm \sqrt{\left(\frac{R}{L}\right)^2 - \frac{4}{LC}}}{2 \times 1} \\ &= \frac{-R}{2L} \pm \sqrt{\frac{R^2}{4L^2} - \frac{1}{LC}} \\ S_1, S_2 &= \frac{-R}{2L} \pm \sqrt{\left(\frac{R}{2L}\right)^2 - \frac{1}{LC}} \end{aligned} \quad \text{-----(15)}$$

Equation (15) can be represented by

$$S_1, S_2 = \alpha \pm \beta$$

$$\text{where, } \alpha = \frac{-R}{2L} \text{ and } \beta = \sqrt{\left(\frac{R}{2L}\right)^2 - \frac{1}{LC}}$$

$$\text{Here, } S_1 = \alpha + \beta, \quad S_2 = \alpha - \beta$$

The natural frequency,  $\omega_n = \frac{1}{\sqrt{LC}}$

Equation (14) can be written as

$$I(s) = \frac{V/L}{(s-s_1)(s-s_2)}$$

$$\text{i.e, } I(s) = \frac{V/L}{[s-(\alpha+\beta)][s-(\alpha-\beta)]} \text{-----(16)}$$

There are three possibilities.

**Case 1 :** when  $\left(\frac{R}{2L}\right)^2 > \frac{1}{LC}$

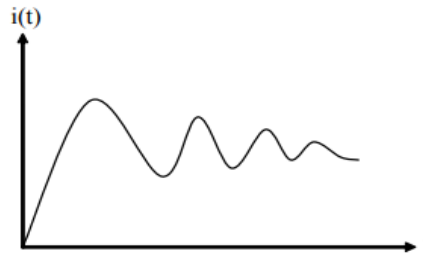
The two roots are real and distinct. The denominator has the roots  $(\alpha + \beta)$  and  $(\alpha - \beta)$  and we may write

$$I(s) = \frac{k_1}{s-(\alpha+\beta)} + \frac{k_2}{s-(\alpha-\beta)}$$

Taking inverse laplace transform,

$$\begin{aligned} i(t) &= k_1 e^{(\alpha+\beta)t} + k_2 e^{(\alpha-\beta)t} \\ &= e^{\alpha t} [k_1 e^{\beta t} + k_2 e^{-\beta t}] \end{aligned} \text{-----(17)}$$

The value of  $k_1$  and  $k_2$  can be find by using partial fraction method. The current is said to be overdamped as in below fig. 4.11.



**Fig. 3.11 Overdamped response**

**Case 2 :** When  $\left(\frac{R}{2L}\right)^2 = \frac{1}{LC}$

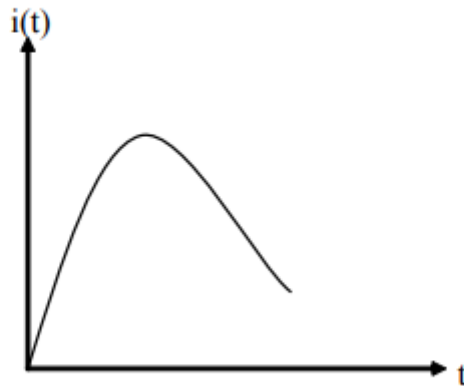
The roots are equal and the oscillation in the circuit are just eliminated. The solution is the critically damped case.

$$I(S) = \frac{k_1}{(s-\alpha)^2} + \frac{k_2}{(s-\alpha)}$$

Taking inverse laplace transform,

$$i(t) = k_1 t e^{\alpha t} + k_2 e^{\alpha t} = e^{\alpha t} [k_1 t + k_2]$$

The current response of  $i(t)$  for critically damped case is shown below.



*Fig. 3.12 Critically damped response*

**Case 3 :**

$$\text{When } \left(\frac{R}{2L}\right)^2 < \frac{1}{LC}$$

The roots are complex conjugate and the circuit is under damped as shown below.

$$I(S) = \frac{k_1}{s - (\alpha + j\beta)} + \frac{k_2}{s - (\alpha - j\beta)}$$

Taking inverse laplace transform,

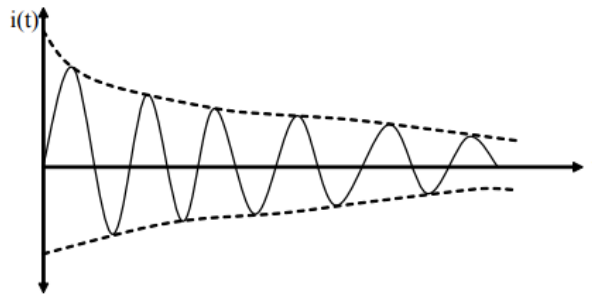
$$\begin{aligned} i(t) &= k_1 e^{(\alpha + j\beta)t} + k_2 e^{(\alpha - j\beta)t} \\ &= e^{\alpha t} [k_1 e^{j\beta t} + k_2 e^{-j\beta t}] \end{aligned}$$

Where,  $k_1$  and  $k_2$  are complex and are also conjugate of one another.

$$k_2 = k_1^*$$

$\therefore$   $i$  can be rewritten as,  $i = e^{\alpha t} [A \cos \beta t + B \sin \beta t]$

This solution shows that the current is oscillatory and at the same time decays in a short time as  $\alpha = -R/2L$  is always negative.



*Fig. 3.13 Oscillatory response*

**Note :** When the terms  $\left(\frac{R}{2L}\right)^2$  and  $\frac{1}{LC}$  are equal the oscillations are just eliminated and this condition is called “critical damping”.