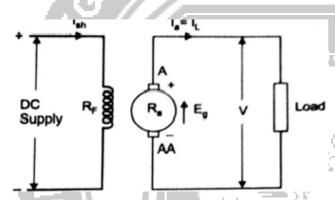
3.7 TYPES OF DC MOTOR:

- 1. Separately excited DC motor
- 2. Self-excited dc motor
 - Series motor
 - Shunt motor
 - Compound motor
 - 1. Long shunt compound motor
 - 2. Short shunt compound motor

SEPARATELY EXCITED DC MOTOR:



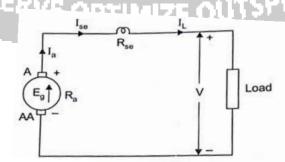
- Field winding and armature are separated.
- Field winding is excited by a separate DC source-separately excited dc motor.
- Ia=Il
- $E_b = V-Ia Ra-Vbrush$

DC SERIES MOTOR:

- Rse –resistance of series field winding-small.

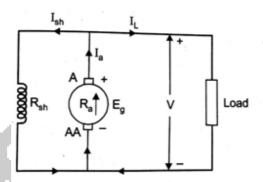
 Il=line current
 Ia=series field Field winding is connected in series with armature.

- Ia=series field
- $V=E_b + Ia Ra + IscRsc + V brush.$
- $V = E_b + (Ra + Rse)$.
- Φα Ise α Ia



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DC SHUNT MOTOR:

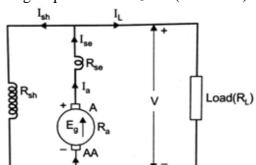


- Field winding is connected across the armature.
- More number of turns with less cross-sectional area.
- Rsh is the shunt field winding
- Ra is the armature resistance.
- Ra is small, Rsh is large.
- Voltage v=voltage across the armature and field winding.
- Il is the line current, divided into two paths
- 1. Field winding
- 2. Armature winding
- II = Ia + Ish
- Ia = armature current
- Ish =shunt field current
- Ish = V/Rsh
- $V = E_b + Ia Ra + V brush$
- $\Phi \alpha$ Ish
- Input is constant, so flux is constant.
- Also known as constant flux motor. TULAM, KANYAKUMARI

DC COMPOUND MOTOR:

1. LONG SHUNT:

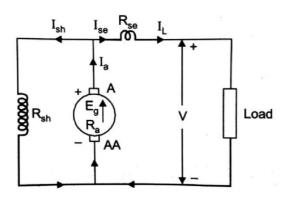
- Shunt field winding is connected to both the armature and the field winding.
- II = Isc + IshIMIZE OUTSPREAD
- Ise = Ia
- II = Ia + Ish
- Ish = V/Rsh
- Voltage equation $V = E_b + Ia(Ra + Rse) + V$ brush



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2. SHORT SHUNT:



- Shunt field winding is connected across armature and series field winding is connected in series.
- II = Ise
- II = Ia + Ish
- Il = Ise = Ia + Ish
- Voltage drop= v –Il Rse
- $V = E_b + Ia Ra + V brush$
- Ish = V- IlRse/ Rsh.

* ARULAM, KANYAKUMARI

OBSERVE OPTIMIZE OUTSPREAD