

**EC 3352 – DIGITAL SYSTEM DESIGN****UNIT – V : LOGIC FAMILIES AND PROGRAMMABLE LOGIC DEVICES****5.5 RTL****Introduction**

Transistor-Transistor Logic (TTL) and Emitter Coupled Logic (ECL) are the most commonly used bipolar logic families. Bipolar logic families use semiconductor diodes and bipolar junction transistors as the basic building blocks of logic circuits. Simplest bipolar logic elements use diodes and resistors to perform logic operation; this is called diode logic. Many TTL logic gates use diode logic internally, and boost their output drive capability using transistor circuits. Other TTL gates use parallel configurations of transistors to perform logic functions. It turned out at the time of introducing TTL circuits that they were adaptable to virtually all forms of IC logic and produced the highest performance-to-cost ratio of all logic types. In view of its versatility a variety of subfamilies (Low Power, High Frequency, Schottky) representing a wide range of speed-power product have also been introduced. The Schottky family has been selected by the industry to further enhance the speed-power product. In Schottky family circuits, a Schottky diode is used as a clamp across the base-collector junction of a transistor to prevent it from going into saturation, thereby reducing the storage time. Several sub-families have evolved in the Schottky TTL family to offer several speed-power products to meet a wide variety of design requirements. These sub-families are:

- Low-power Schottky TTL (LSTTL)
- Fairchild Advanced Schottky TTL (FAST)
- Advanced Low Power Schottky TTL (ALSTTL)
- Advanced Schottky TTL (ASTTL)

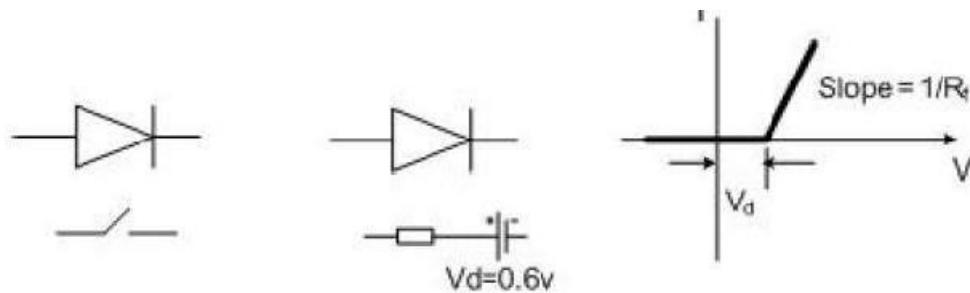
We will explore the characteristics of the TTL family in this Learning Unit.

**Diodes**

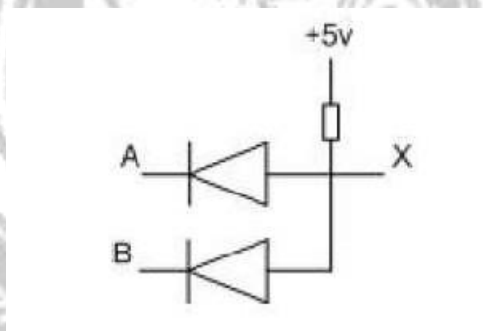
A semiconductor diode is fabricated from two types, p-type and n-type, of semiconductor material that are brought into contact with each other. The point of contact between the p and n materials is called p-n junction. Actually, a diode is

fabricated from a single monolithic crystal of semiconductor material in which the two halves are doped with different impurities to give them p-type and n-type properties. A real diode can be modelled as shown in the figure 1.

- It is an open circuit when it is reverse biased (we ignore its leakage current)
- It acts like a small resistance,  $R_f$ , called the forward resistance, in series with  $V_d$ , called a diode drop, a small voltage source.
- The forward diode drop would be about 0.6 V and  $R_f$  is about 25  $\Omega$ .



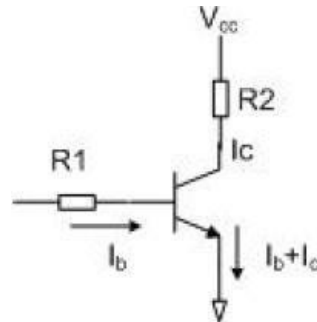
Diode action is exploited to perform logical operations. The circuit shown in the figure 2 performs AND function if 0-2 V (Low) input is considered logic 0 and 3-5 V (High) input is considered as logic 1. When both A and B inputs are High, the output X will be High. If any one of the inputs is at Low level, the output will also be at Low level.



### **Bipolar Junction Transistor**

A bipolar junction transistor is a three terminal device and acts like a current-controlled switch. If a small current is injected into the base, the switch is “on”, that is, the current will flow between the other two terminals, namely, collector and emitter. If no current is put into the base, then the switch is “off” and no current flows between the

emitter and the collector. A transistor will have two p-n junctions, and consequently it could be pnp transistor or npn transistor. An npn transistor, found more commonly in IC logic circuits, is shown in the figure 3 in its common-emitter configuration.



The relations between different quantities are given as

in the following:  $I_b = (V_{IN} - 0.6)/R_1$

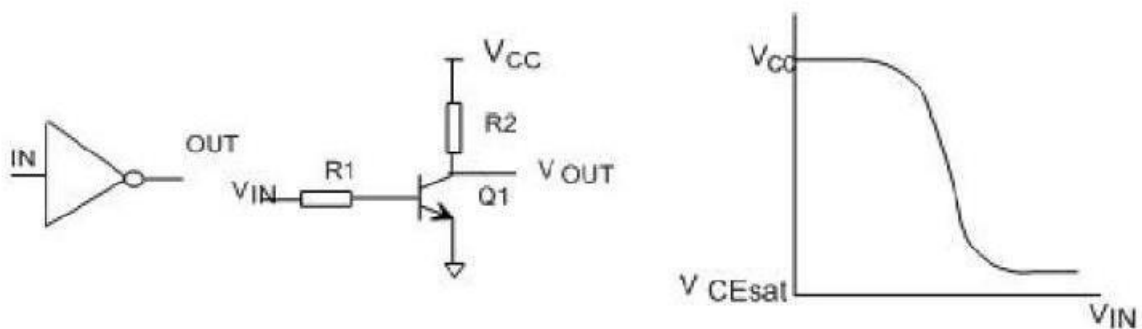
$$I_C = \beta \cdot I_b$$

$$V_{CE} = V_{CC} - I_C \cdot R_2$$

$$= V_{CC} - \beta \cdot I_b \cdot R_2$$

$$= V_{CC} - \beta(V_{IN} - 0.6) \cdot R_2/R_1$$

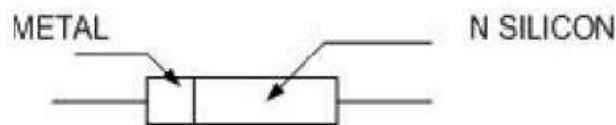
where  $\beta$  is called the gain of the transistor and is in the range of 10 to 100 for typical transistors. Figure 4 shows a logic inverter from an npn transistor in the common-emitter configuration. When the input voltage  $V_{IN}$  is Low, the output voltage is High, and vice versa.



When the input of a saturated transistor is changed, the output does not change immediately; it takes extra time, called storage time, to come out of saturation. In fact, storage time accounts for a significant portion of the propagation delay in the earlier TTL families. Present day TTL logic families reduce this storage time by placing a Schottky diode between the base and collector of each transistor that might saturate.

### **Schottky Barrier Diode**

A Schottky Barrier Diode (SBD) is illustrated in figure 5. It is a rectifying metalsemiconductor contact formed between a metal and highly doped N semiconductor.



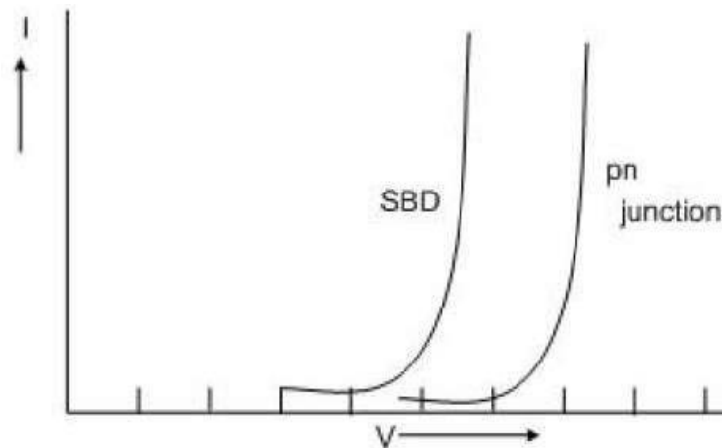
The valence and conduction bands in a metal overlap making available a large number of free-energy states. The free-energy states can be filled by any electrons which are injected into the conduction band. A finite number of electrons exist in the conduction band of a semiconductor.

The number of electrons depends mainly upon the thermal energy and the level of impurity atoms in the material. When a metal-semiconductor junction is formed, free electrons flow across the junction from the semiconductor, via the conduction band, and fill the free-energy states in the metal. This flow of electrons builds a depletion potential across the barrier. This depletion potential opposes the electron flow and, eventually, is sufficient to sustain a balance where there is no net electron flow across the barrier. Under the forward bias (metal positive), there are many electrons with enough thermal energy to cross the barrier potential into the metal. This forward bias is called “hot injection.” Because the barrier width is decreased as forward bias  $V_F$  increases, forward current will increase rapidly with an increase in  $V_F$ .

When the SBD is reverse biased, electrons in the semiconductor require greater energy to cross the barrier. However, electrons in the metal see a barrier potential from the side essentially independent of the bias voltage and small net reverse current will flow. Since this current flow is relatively independent of the applied reverse bias, the

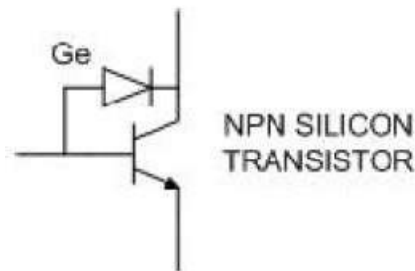
reverse current flow will not increase significantly until avalanche breakdown occurs. A simple metal/semiconductor collector contact is an ohmic contact while the SBD contact is a rectifying contact. The difference is controlled by the level of doping in the semiconductor material. Current in SBD is carried by majority carriers. Current in a p-n junction is carried by minority carriers and the resultant minority carrier storage causes the switching time of a pn junction to be limited when switched from forward bias to reverse bias.

A p-n junction is inherently slower than an SBD even when doped with gold. Another major difference between the SBD and p-n junction is forward voltage drop. For diodes of the same surface area, the SBD will have a larger forward current at the same forward bias regardless of the type of metal used. The SBD forward voltage drop is lower at a given current than a p-n junction. Figure 6 illustrates the forward current-voltage characteristic differences between the SBD and p-n junction.

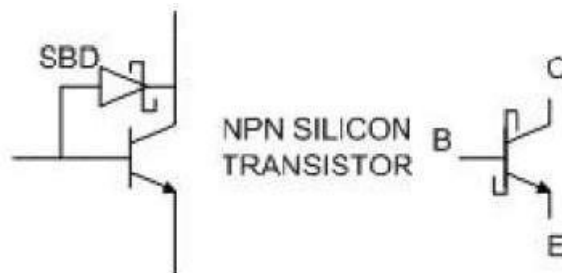


### Schottky Transistor

The Schottky transistor makes use of two earlier concepts: Baker clamp and the Schottky Barrier-Diode (SBD). The Schottky clamped transistor is responsible for increasing the switching speed. The use of Baker Clamp, shown in the figure 7, is a method of avoiding saturation of a discrete transistor.



The germanium diode forward voltage is 0.3 V to 0.4 V as compared to 0.7 V for the base-emitter junction silicon diode. When the transistor is turned on, base current drives the transistor toward saturation. The collector voltage drops, the germanium diode begins to conduct forward current, and excess base drive is diverted from the base-collector junction of the transistor. This causes the transistor to be held out of deep saturation, the excess base charge not stored, and the turn-off time to be dramatically reduced. However, a germanium diode cannot be incorporated into a monolithic silicon integrated circuit. Therefore, the germanium diode must be replaced with a silicon diode which has a lower forward voltage drop than the base-collector junction of the transistor. A normal p-n diode will not meet this requirement. An SBD can be used to meet the requirement as shown in the figure 8.



The SBD meets the requirements of a silicon diode which will clamp a silicon npn transistor out of saturation.

### **BASIC NAND GATE**

The familiarization with a logic family is acquired, in general, through understanding the circuit features of a NAND gate. The circuit diagram of a two-input LSTTL NAND gate, 74LS00, is shown in the figure 9. D1 and D2 along with 18 K $\Omega$  resistor perform the AND function. Diodes D3 and D4 do nothing in normal operation,

but limit undesirable negative excursions on the inputs to a signal diode drop. Such negative excursions may occur on High- to-Low input transitions as a result of transmission-line effects. Transistor Q1 serves as an inverter, so the output at its collector represents the NAND function. It also, along with its resistors, forms a phase splitter that controls the output stage. The output state has two transistors, Q3 and Q4, only one of which is on at any time. The TTL output state is sometimes called a totem-pole output. Q2 and Q5 provide active pull-up and pull-down to the High and Low states, respectively. Transistor Q5 regulates current flow into the base of Q4 and aids in turning Q4 off rapidly. Transistors Q3 and Q2 constitute a Darlington driver, with Q3 not being permitted to saturate. The network consisting of Schottky diodes D3 and D4 and a 5 K $\Omega$  resistor is connected to the output and aids in charging and discharging load capacitance when Q3 and Q4 are changing states. Transistor Q4 conducts when the output is in Low state.

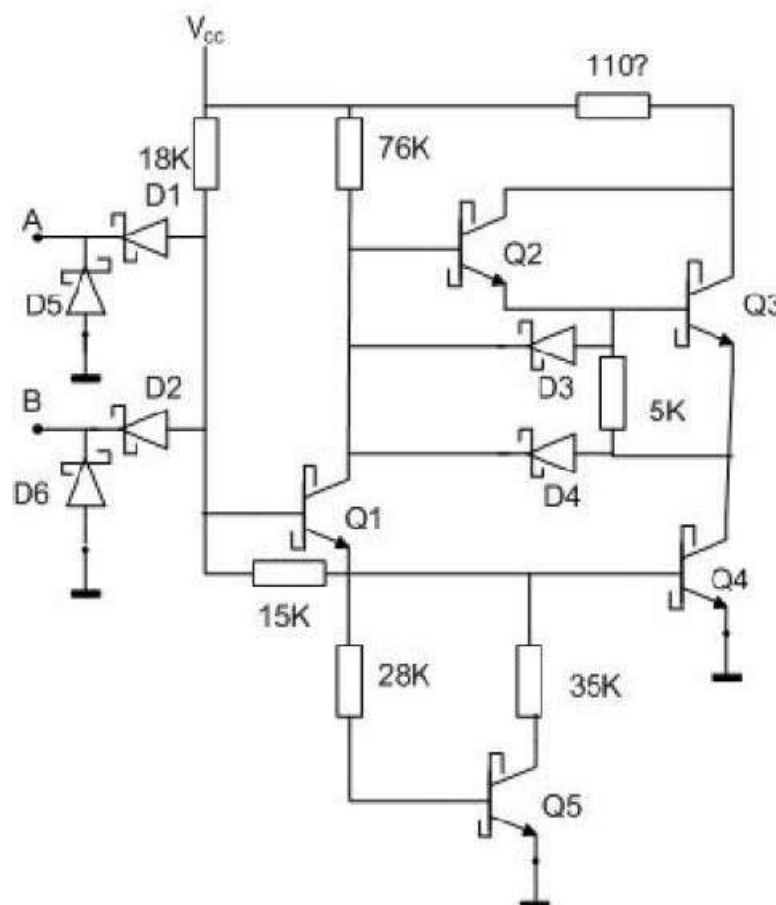
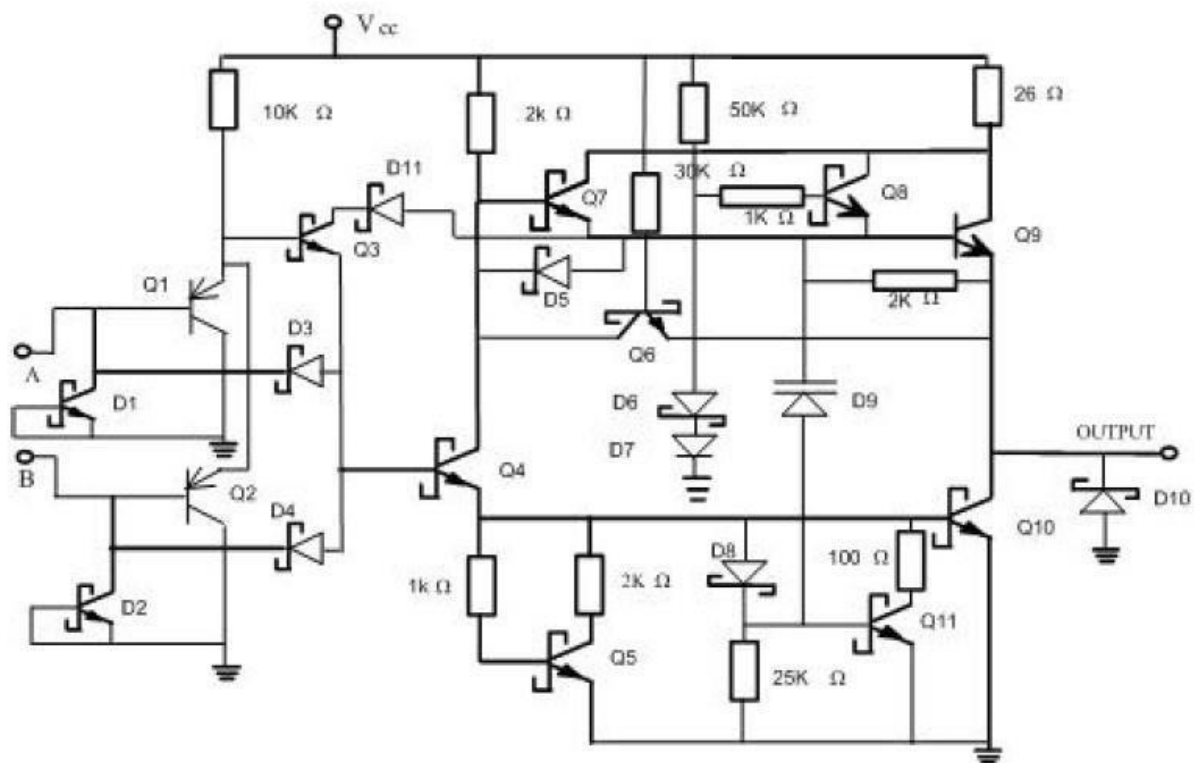


Figure 11 shows one gate in 74ALS00A quad 2-input NAND gate parallel-connected pnp transistors Q1 and Q2 are used at the input. These transistors reduce the

current flow,  $I_R$ , when the inputs are low and thus increase fan out. If inputs A, B, or both are low, then the respective pnp transistors turn on because their emitters are then more positive than their bases. If at least one of the inputs is low, the corresponding pnp transistor conducts, making the base of Q3 low and keeping Q3 off. If both the inputs A and B are high, both switches are open and Q3 turns on. Q3 drives Q4 (by emitter follower action), and Q4 drives the output totem pole. Schottky diodes D3, D4 and D5 are used to speed the switching and do not affect the logic. Note that the output and the inputs have Schottky protective diodes. Figure 12 shows one gate in 74AS00 gate.



## CMOS FAMILY

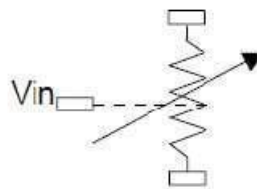
CMOS has often been called the ideal technology. It has low power dissipation, high noise immunity to power supply noise, symmetric switching characteristics and large supply voltage tolerance. Reducing power requirements leads to reduction in the cost of power supplies, simplifies power distribution, possible elimination of cooling fans and a denser PCB, ultimately leading to lower cost of the system. Though the operation of a MOS transistor was understood long before bipolar transistor was invented, its fabrication could not be monitored. Consequently development of MOS



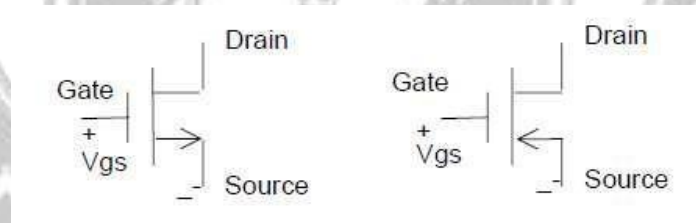
circuits lagged bipolar circuits considerably, and initially they were attractive only in selected applications. In recent years, advances in the design of MOS circuits have vastly increased their performance and popularity. By far majority of the large scale integrated circuits such as microprocessors and memories use CMOS. The usage of CMOS logic is increasing in applications that use small and medium scale integrated circuits as CMOS circuits, while offering functionality and speed similar to bipolar logic circuits, consume very much less power.

## CMOS LOGIC CIRCUITS

The basic building blocks in CMOS logic circuits are MOS transistors. A MOS transistor can be received as a 3-terminal device that acts like a voltage-controlled resistance, as shown in the figure 1.



An input voltage applied to one terminal controls the resistance between the remaining two terminals. In digital applications, a MOS transistor is operated so its resistance is always either very high (and the transistor “off”) or very low (and the transistor is always “on”). There are two types of MOS transistors n-channel and pchannel. The circuit symbols for NMOS and PMOS transistors are shown in the figure 2.

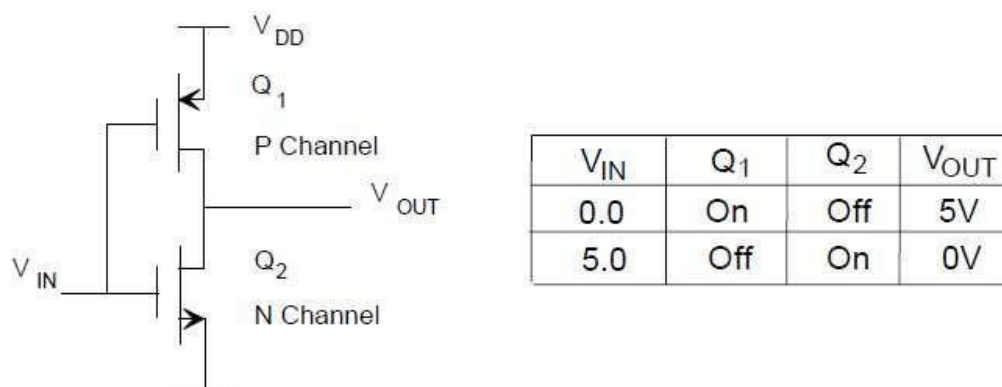


The terminals are called gate, source and drain. The voltage from gate to source ( $V_{GS}$ ) in NMOS device is normally zero or positive. If  $V_{GS} = 0$  then the resistance from drain to source ( $R_{DS}$ ) is very high, of the order of mega ohm or more. When  $V_{GS}$  is made positive  $R_{DS}$  can decrease to a very low value, of the order of 10 ohms. In

the PMOS transistor  $V_{GS}$  is normally zero or negative. If  $V_{GS}$  is zero, then the resistance from source to drain ( $R_{DS}$ ) is very large, and when  $V_{GS}$  is negative  $R_{DS}$  can decrease to a very low value. The gate of a MOS transistor has very high impedance, as it is separated from the source and drain by an insulating material with a very high resistance. However, the gate voltage creates an electric field that enhances or retards the flow of current between source and drain. This is the “field effect” in a MOSFET. The high resistance between the gate and the other terminals keeps the gate current to values lower than a microampere irrespective of the gate voltage. This current is called “leakage current”. The gate of a MOS transistor is capacitively coupled to the source and drain. In high speed circuits, the power needed to charge and discharge these capacitances on each input signal transition accounts for a non trivial portion of a circuit’s power consumption.

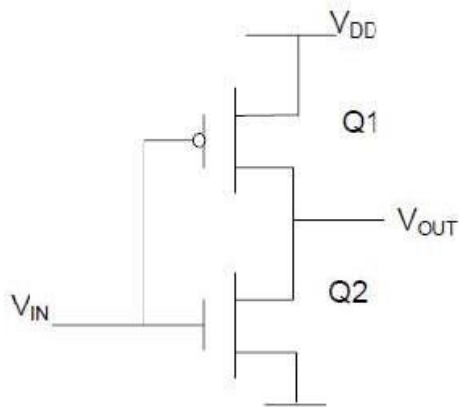
### **Basic CMOS Inverter circuit:**

NMOS and PMOS transistors are used together in a complementary way to form CMOS logic, as shown in the figure 3. The power supply voltage  $V_{DD}$ , typically is in the range of 2- 6 V, and is most often set at 5.0 V for compatibility with TTL circuits.



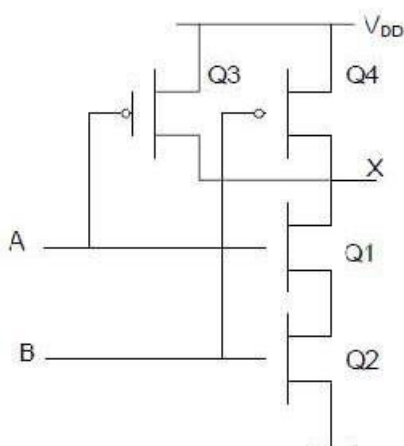
When  $V_{IN}$  is at 0.0 V, the lower n-channel MOSFET Q1 is OFF since its  $V_{GS}$  is 0, but the upper p-channel MOSFET Q2 is ON since its  $V_{GS}$  would be -5.0 V. Consequently Q2 presents a small resistance while Q1 presents a large resistance.  $V_{OUT}$  at the output terminal would be +5.0 V. Similarly when  $V_{IN}$  is at 5.0 Q1 will be ON presenting a small resistance to ground while Q2 will be OFF presenting a large resistance. The output terminal voltage ( $V_{OUT}$ ) would be 0 V. Obviously this circuit behaves as an inverter. As we associated a logic state 0 or 1 with a voltage, we can say when the input signal is asserted Q1 is ON and Q2 is OFF, and when the input signal is

not asserted Q1 is OFF and Q2 is ON. We make use of this interpretation to further simplify the circuit representation of MOSFETs, as shown in the figure 4. The bubble convention goes along with the convention followed in drawing logic diagrams.

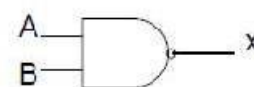


**CMOS NAND and NOR gates:**

Logic gates can be realised using CMOS circuits. A k-input gate uses k p-channel MOSFETs and k n-channel MOSFETs. Figure 5 shows a 2-input NAND gate. If either input is Low, the output X is High with low impedance connection to VDD through the corresponding p-channel transistor, and the path to the ground is blocked by the corresponding OFF n-channel MOSFET. If both inputs are High, the two n-channel MOSFETs are ON and the two p- channel MOSFETs are OFF. This is the operation required for the circuit to function as a NAND gate.

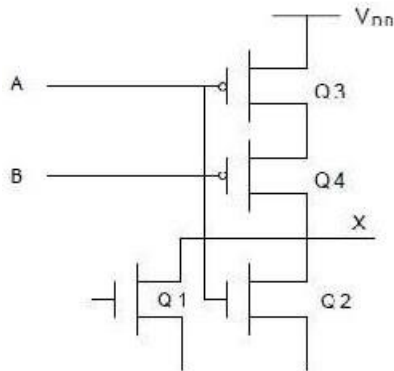


A	B	Q1	Q2	Q3	Q4	X
L	L	OFF	OFF	ON	ON	H
L	H	OFF	ON	ON	OFF	H
H	L	ON	OFF	OFF	ON	H
H	H	ON	ON	OFF	OFF	L

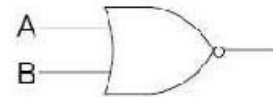


A 2-input NOR gate is shown in figure 6. Only when A and B are Low the output X is

High and for all other combination of input levels the output is Low.



A	B	Q1	Q2	Q3	Q4	X
L	L	OFF	OFF	ON	ON	H
L	H	OFF	ON	ON	OFF	L
H	L	ON	OFF	OFF	ON	L
H	H	ON	ON	OFF	OFF	L

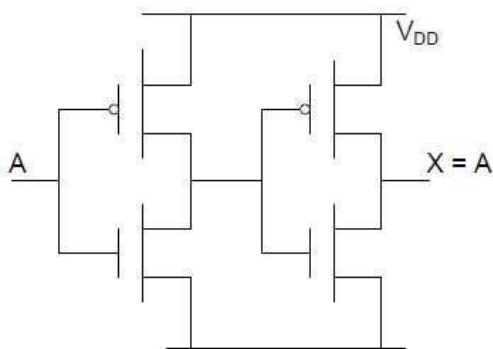


**Non Inverting Gates:**

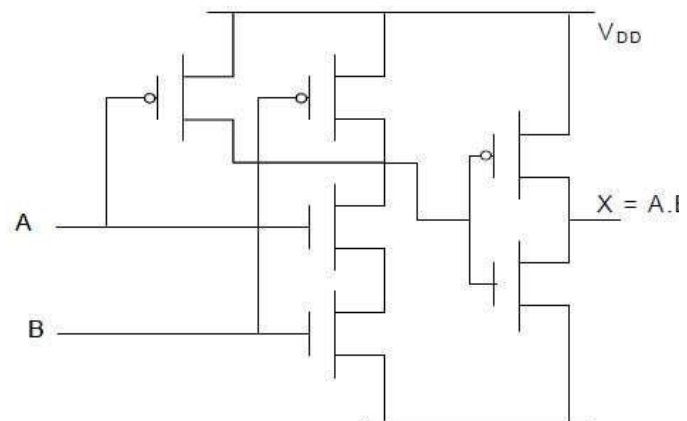
In all logic families, the simplest gates are inverters, and the next simplest are NAND and NOR gates. It is typically not possible to design a non-inverting gate with a smaller number of transistors than an inverting one. CMOS non-inverting buffers and AND and OR gates are obtained by connecting an inverter to the output of the corresponding inverting gate. Figure 7 shows a non inverting buffer and an AND gate

**Buffering:**

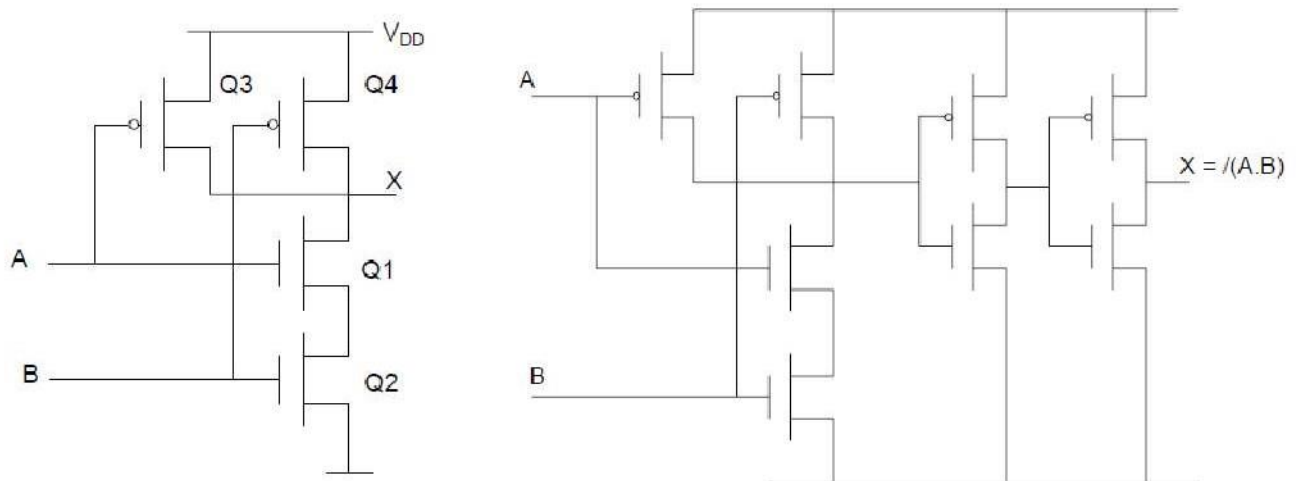
Most of the CMOS families are buffered. Buffering CMOS logic merely denotes designing the IC so that the output is taken from an inverting buffer stage. An unbuffered and buffered NAND gates are illustrated in the figure 8.



Buffer



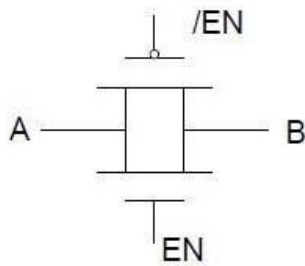
AND gate



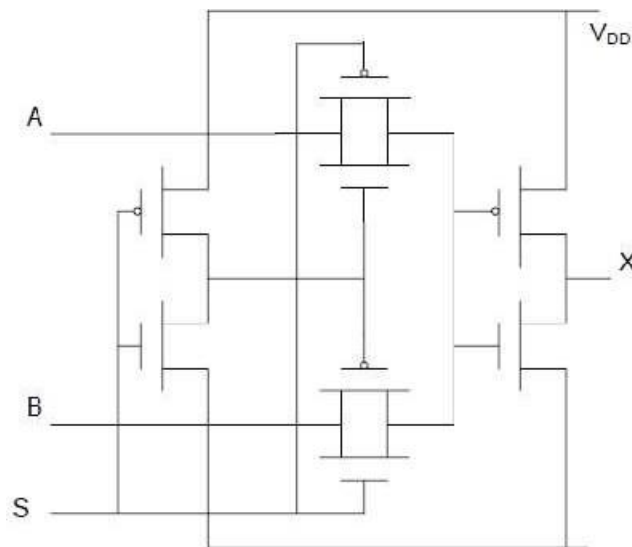
There are several advantages to buffering. By using the standardised buffer, the output characteristics of all devices are more easily made identical. Multistage gates will have better noise immunity due to their higher gain caused by having several stages from input to output. Also, the output impedance of an unbuffered gate may change with input logic level voltage and input logic combination, whereas buffered output are unaffected by input conditions. Single stage gates implemented would require large transistors due to the large output drive requirements. These large devices would have a large input capacitance associated with them. This would affect the speed of circuits driving into an unbuffered gate, especially when driving large fan outs. Buffered gates have small input transistors and correspondingly small input capacitances. One may think that a major disadvantage of buffered circuits would be speed loss. It would seem that a two or three stage gate would be two to three times slower than a buffered one. However, internal stages are much faster than the output stage and speed lost by buffering is relatively small.

**Transmission Gates:**

A p-channel and n-channel transistor pair can be used as a logic-controlled switch. This circuit, shown in the figure 9, is called a CMOS transmission gate.



A transmission gate is operated so that its input signals EN and /EN are always at opposite levels. When EN is High and /EN is Low, there is a low impedance connection (as low as  $5\ \Omega$ ) between points A and B. When EN is Low and /EN is High, points A and B are disconnected. Once transmission gate is enabled, the propagation delay from A to B (or vice versa) is very short. Because of their short delays and conceptual simplicity, transmission gates are often used internally in larger-scale CMOS devices such as multiplexers and flip-flops. For example, figure 10 shows how transmission gates can be used to create a 2-input multiplexer



When S is Low, the B is connected to X, and when S is High, A is connected to X. While it may take some nanoseconds for the transmission gate to change its state, the propagation delay from input to output of the gate would be very small.

## **CMOS LOGIC FAMILIES**

The first commercially successful CMOS family was 4000-series CMOS. Although 4000-series circuits offered the benefit of low power dissipation, they were fairly slow and were not easy to interface with the most popular logic family of the time, bipolar TTL. Thus, the 4000 series was supplanted in most of applications by CMOS families that had better performance characteristics. The first two 74-series CMOS families are HC (High-speed CMOS) and HCT (High-speed CMOS, TTL compatible). HC and HCT both have higher speed and better current sinking and sourcing capability. The HCT family uses a power supply voltage  $V_{DD}$  of 5 V and can be intermixed with TTL device, which also use a 5-V supply. The HC is mainly optimised for use in systems that use CMOS logic exclusively, and can use any power supply voltage between 2 and 6 V.

A higher voltage is used for higher speed, and lower voltage for lower power dissipation. Lowering the supply voltage is especially effective, since most CMOS power dissipation is proportional to the square of the voltage ( $CV^2 f$ ). Even when used with a 5 V power supply, HC devices are not quite compatible with TTL. In particular, HC circuits are designed to recognise CMOS input levels. The output levels produced by TTL devices do not quite match this range, so HCT devices use the different input levels. These levels are established in the fabrication process by making transistors with different switching threshold, producing the different transfer characteristics. Two more CMOS families, known as AC (Advanced CMOS) and ACT (Advanced CMOS, TTL compatible) were introduced in mid-1980s. These families are fast, comparable to ALSTTL, and they can source or sink more current than most of the TTL circuits can. Like HC and HCT, the AC and ACT families differ only in the input levels that they recognise; their output characteristics are the same. Also like HC/HCT, AC/ACT outputs have symmetric output drive.

In the early 1990s, yet another CMOS family was launched. The FCT (Fast CMOS, TTL compatible) family combines circuit innovations with smaller transistor geometries to produce devices that are even faster than AC and ACT while reducing power consumption and maintaining full compatibility with TTL. There are two subfamilies, FCT-T and FCT2-T. These families represent a “technology crossover point” that occurred when the performance achieved using CMOS technology matched

that of bipolar technology, and typically one third the power. Both the logic families are TTL compatible, which means that they conform to the industry-standard TTL voltage levels and threshold point (1.5 V), and operate from a 5 Volt VCC power source. All inputs are designed to have a hysteresis of 200 mV (low-to-high threshold of 1.6 V and high-to-low threshold of 1.4V). This hysteresis increases both the static and dynamic noise immunity, as well as reducing the sensitivity to noise superimposed on slowly rising or falling inputs. Individual logic gates are not manufactured in the FCT families. Just about the simplest FCT logic element is a 74FCT138/74FCT138T decoder, which has six inputs, eight outputs and contains the equivalent of about twelve 4-input gates internally

### **ELECTRICAL BEHAVIOUR OF CMOS CIRCUITS**

This section presents the electrical characteristics of CMOS families. The electrical characteristics refer to DC noise margins, fan out, speed, power consumption, noise, electrical discharge, open drain outputs and three state outputs. Logical Levels and Noise Margins: The generated voltage levels given by the manufacturing data sheet for HCMOS circuits operating at  $V_{DD} = 5\text{ V}$ , are given in the Table 1. The input parameters are mainly determined by the switching threshold of the two transistors, while the output parameters are determined by the ON resistance of the transistors. These parameters apply when the device inputs and outputs are connected only to other CMOS devices. The dc voltage levels and noise margins of CMOS families are given in the Table 1.

TABLE 1: DC Characteristics of CMOS Families

Family	$V_{IHMIN}$	$V_{ILMAX}$	$V_{OHMIN}$	$V_{OLMAX}$	NM LOW @ $V_{CC} = 5V$	NM HIGH @ $V_{CC} = 5V$	Units
4000B	$\frac{2}{3}V_C$	$\frac{1}{3}V_C$	$V_{CC}-0.1$	0.01	1.6	1.6	V
HCMOS	3.5	1.5	$V_{CC}-0.1$	0.1	1.4	1.4	V
HCTMOS	2	0.8	$V_{CC}-0.1$	0.1	0.7	2.4	V
ACMOS	3.5	1.5	$V_{CC}-0.1$	0.1	1.4	1.4	V
ACTMOS	2	0.8	$V_{CC}-0.1$	0.1	0.7	2.4	V
FCT	2	0.7	2.4	0.5	0.2	0.4	V



These dc noise margins are significantly better than those associated with TTL families. As CMOS circuits can be operated with  $V_{DD} = 2\text{ V}$  to  $V_{DD} = 6\text{ V}$  the voltage levels associated with CMOS gates may be expressed as

$$V_{IL}(\text{max}) = 30\%$$

$$V_{DD} V_{OH}(\text{min})$$

$$= V_{DD} - 0.1\text{ V}$$

$$V_{IH}(\text{min}) = 70\%$$

$$V_{DD}$$

Regardless of the voltage applied to the input of a CMOS inverter, the input currents are very small. The maximum leakage current that can flow, designated as  $I_{I\text{max}}$ , is  $+1\mu\text{A}$  for HCMOS with  $5\text{ V}$  power supply. As the load on a CMOS gate could vary, the output voltage would also vary. Instead of specifying the output impedance under all conditions of loading the manufacturers specify a maximum load for the output in each state, and guarantee a worst-case output voltage for that load. The load is specified in terms of currents. The input and output currents are given in the Table 2.

TABLE 2: Input and Output Current Levels of CMOS Families

CMOS Families	Input currents		Output currents		Units
	$I_{IH}$	$I_{IL}$	$I_{OH}$	$I_{OL}$	
4000b +5	<u>0.001</u>	0.001	-1.6@2.5 V	0.4@0.4 V	mA
74HC	0.001	-0.001	-4 @ $V_{CC}-0.8$	4@0.4	mA
74HCT	0.001	0.001	-4@ $V_{CC}-0.8$	4@ 0.4 V	mA
74AC	0.001	-0.001	-24 @ $V_{CC}-0.8$	24@0.4 V	mA
74ACT	0.001	-0.001	-24 @ $V_{CC}-0.8$	24 @0.4 V	mA
74FCT	0.005	-0.005	-15@ 2.4 V	48@0.5 V	mA

These specifications are given at voltages which are normally associated with TTL gates. If the current drawn by the load is smaller, the voltage levels would

improve significantly. This happens when CMOS gates are connected to CMOS loads. It is important to note that in a CMOS circuit the output structure by itself consumes very little current in either state, High or Low. In either state, one of the transistors is in the high impedance OFF state. When no load is connected the only current that flows through the transistors is their leakage current. With a load, however, current flows through both the load and the ON transistor, and power is consumed in both.

### **Fan out:**

The fan out of a logic gate is the number of inputs that the gate can drive without exceeding its worst- case loading specifications. The fan out depends not only on the characteristics of the output, but also on the inputs that it is driving. When a HCMOS gate is driving HCMOS gates, we note that  $I_{ILmax}$  is  $+1 \mu A$  in any state, and  $I_{OHmax} = -20 \mu A$  and  $I_{OLmax} = 20 \mu A$ . Therefore, the Low-state fan out is 20 and High-state fan out is 20 for HCMOS gates. However, if we are willing to work with slightly degraded output voltages, which would reduce the available noise margins, we can go for  $I_{OHmax}$  and  $I_{OLmax}$  of 4.0 mA. This would mean that an HCMOS gate can drive as many as 4000 HCMOS gates. But in actuality this would not be true, as the currents we are considering are only the steady state currents and not the transition currents. The actual fan out under degraded load conditions would be far less than 4000. During the transitions, the CMOS output must charge or discharge the capacitance associated with the inputs that it drives. If this capacitance is too large, the transition from Low to High (or vice versa) may be too slow causing improper system operation.

### **CMOS DYNAMIC ELECTRICAL BEHAVIOUR**

Both the speed and the power consumption of CMOS devices depend on to a large extent on AC or dynamic characteristics of the device and its load, that is, what happens when the output changes between states. The speed depends on two factors, transition times and propagation delay. The rise and fall times of an output of CMOS IC depend mainly on two factors, the ON transistor resistance and the load capacitance. The load capacitance comes from three different sources: output circuits including a gate's output transistors, internal wiring and packaging, have capacitances associated with them (of the order of 2-10 pF); wiring that connects an output to other inputs (about 1pF per inch or more depending on the wiring technology); and input circuits including transistors, internal wiring and packaging (2-15 pF per input). The OFF transistor resistance would be about 1 M $\Omega$ , the ON resistance of p-channel transistor

would be of the order of  $200 \Omega$ , and the ON resistance of n-channel resistance would be about  $100 \Omega$ . We can compute the rise and fall times from the equivalent circuits. Several factors lead to nonzero propagation delays. In a CMOS device, the rate at which transistors change state is influenced both by the semiconductor physics of the device and by the circuit environment including input-signal transition rate, input capacitance, and output loading. The speed characteristics of CMOS families are given in the Table 3.

TABLE 3: Speed Characteristics of CMOS families

Family	Prop. Delay (ns)	Flip-Flop frequency (MHz)
4000B	160	5
HCMOS	22	25
HCTMOS	24	25
ACMOS	8.5	45
ACTMOS	8	45
FCTMOS	5.8(138)	60

Device outputs in AC and ACT families have very fast rise and fall times. Input signals should have rise and fall times of 3.0 ns (400 ns for HC and HCT devices) and signal swing of 0V to 3.0V for ACT devices or 0V to VDD for AC devices. Obviously such signal transition times are a major source of analog problems, including switching noise and “ground bounce”.

### **Power Consumption:**

A CMOS circuit consumes significant power only during transition, that is dynamic power dissipation is more. One source of dynamic power dissipation is the partial short-circuiting of the CMOS output structure. When the input voltage is changing from one state to the other, both the p-channel and nchannel output transistors may be partially ON, creating a series resistance of  $600 \Omega$  or less. During this transition period, current flows through the transistors from VDD to ground. The amount of power consumed in this way depends on the value of VDD, the frequency of output transitions, and an equivalent dissipation capacitance CPD as given by the

manufacturer.  $P_T = C_{PD} \cdot V_{DD} \cdot f$   $P_T$  is the internal power dissipation given in watts,  $V_{DD}$  is the supply voltage in volts,  $f$  is frequency of output transitions in Hz, and  $C_{PD}$  is the power dissipation capacitance in farads.  $C_{PD}$  for a gate of HCMOS is about 24 pF. This relationship is valid only if the rise and fall times of the input signal are within the recommended maximum values.

## **ECL Family**

The key to propagation delay in bipolar logic family is to prevent the transistors in a gate from saturating. Schottky families prevent the saturating using Schottky diodes across the base-collector junctions of transistors. It is also possible to prevent saturating by using a structure called Current Mode Logic (CML). Unlike other logic families considered so far, CML does not produce a large voltage swing between low and high levels. Instead, it has a small voltage swing, less than a volt, and it internal switches current between two possible paths depending on the output state.

The first CML logic family was introduced by General Electric in 1961. The concept was refined by Motorola and others to produce today's 10K, 100K Emitter Coupled Logic (ECL) families. These ECL families are fast and offer propagation delays as short as 1 ns. In fact, through out the evolution of digital circuit technology, some type of CML has always been the fastest commercial logic family. However commercial ECL families are not nearly as popular as TTL and CMOS mainly because they consume too much power. In fact, high power consumption has made the design of ECL super computers, such as CRAY as much of a challenge in cooling technology as in digital design. In addition, ECL has poor power-speed product, does not provide a high level of integration, has fast edge rates requiring design for special transmission line effect, and is not directly compatible with TTL and CMOS. But ECL family continues to survive and in applications which require maximum speed regardless of cost.

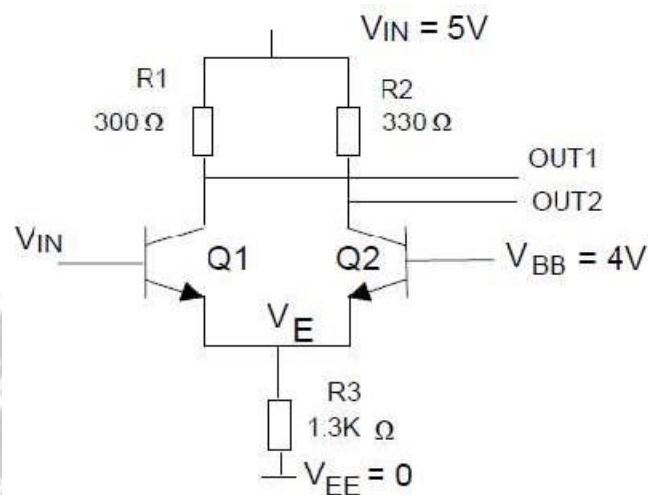
## **ECL Circuits**

### **Basic CML Circuit:**

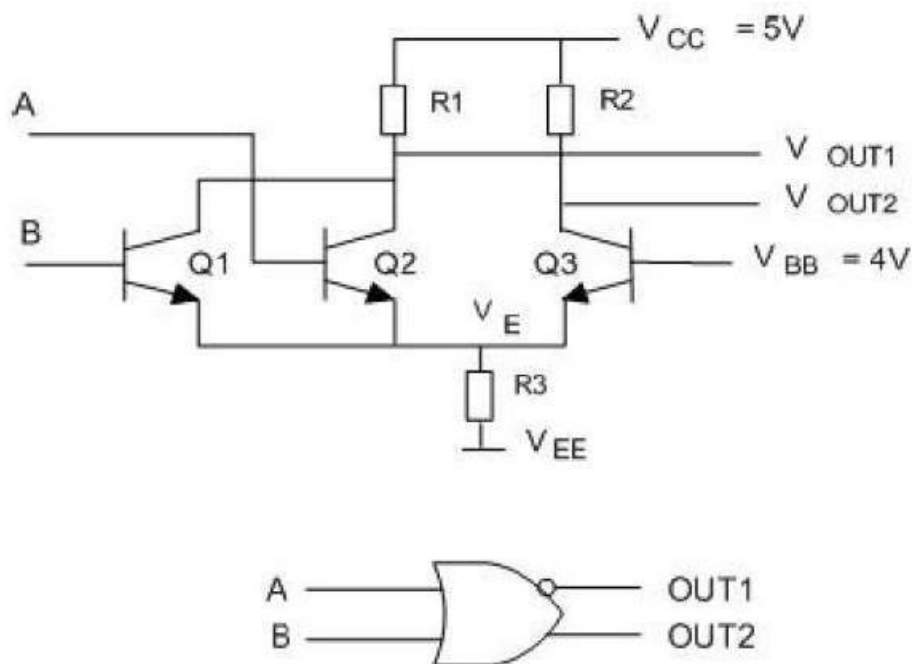
The basic idea of current mode logic is illustrated by the inverter/buffer circuit in the figure 1. This circuit has both inverting (OUT1) and non-inverting output (OUT2). Two transistors are connected as a differential amplifier with a common emitter resistor

R3. Let the supply  $V_{CC} = 5\text{ V}$ ,  $V_{BB} = 4\text{ V}$  and  $V_{EE} = 0\text{ V}$ . Input Low and High levels are defined to be 3.6 and 4.4 V. This circuit produces output Low and High levels 0.6 V higher (4.2 and

5.0 V). When  $V_{IN}$  is high transistor Q1 is ON, but not saturated, and transistor Q2 is OFF. When Q1 is ON  $V_E$  is one diode drop lower than  $V_{IN}$ , or 3.8 V. Therefore, current through R3 is  $(3.8/1.3\text{ K}\Omega)$  2.92 mA. If Q1 has a  $\beta$  of 10, then 2.65 mA of this current comes through the collector and R1, so  $V_{OUT1}$  is 4.2V (Low) since the voltage across Q1 ( $= 4.2 - 3.8 = 0.4\text{ V}$ ) is greater than  $V_{CEsat}$ , Q1 is not saturated Q2 is off because of its base to emitter voltage ( $4.0 - 3.8 = 0.2\text{ V}$ ) is less than 0.6 V. Thus  $V_{OUT2}$  is at 5.0 V (High) as no current passes through R2.



When  $V_{IN}$  is Low, transistor Q1 is OFF, and Q2 is ON but not saturated.  $V_E$  will be one diode drop below  $V_{BB}$  ( $4.0 - 0.6 = 3.4\text{ V}$ ). The current through R3 is  $(3.4/1.3\text{ K}\Omega) = 2.6\text{ mA}$ . The collector current of Q2 is 2.38 mA for a  $\beta$  of 10. The voltage drop across R2 is  $(2.38 \times 0.33) = 0.5\text{ V}$ , and  $V_{OUT2}$  is about 4.2 V. Since the collector emitter voltage of Q2 is  $(4.2 - 3.4) = 0.8\text{ V}$ , it is not saturated. Q1 is off because its base-emitter voltage is  $(3.6 - 3.4) = 0.2$  and is less than 0.6 V. Thus  $V_{OUT1}$  is pulled up to 5.0 V through R1. To perform logic with the basic unit of figure 1, we simply place additional transistors in parallel with Q1. Figure 2 shows a 2-input OR/NOR gate. If any input is High, the corresponding input transistor is active, and  $V_{OUT1}$  is Low (NOR output). At the same time, Q3 is off, and  $V_{OUT2}$  is High (OR output). However, the circuit shown in figure 2 cannot meet the input/output loading requirements effectively.



### ECL SUBFAMILIES

Motorola has offered MECL circuits in five logic families: MECL I, MECL II, MECL III, MECL 10000 (MECL 10K), and MECL 10H000 (MECL 10KH). The MECL I family was introduced in 1962, offering 8 ns gate propagation delay and 30 MHz toggle rates. This was the highest performance from any logic family at that time. However, this family required a separate bias driver package to be connected to each logic function. The ten pin packages used by this family limited the number of gates per package and the number of gate inputs. MECL II was introduced in 1966. This family offered 4 ns propagation delay for the basic gate, and 70 MHz toggle rates. MECL II circuits have a temperature compensated bias driver internal to the circuits, which simplifies circuit interconnections. MECL III was introduced in 1968. They offered 1 ns gate propagation delays and flip-flop toggle rates higher than 500 MHz. The 1 ns rise and fall times required a transmission line environment for all but the smallest systems. For this reason, all circuit outputs are designed to drive transmission lines and all output logic levels are specified when driving 50-ohm loads. For the first time with MECL, internal input pull down resistors are included with the circuits to eliminate the need to tie unused inputs to  $V_{EE}$ .

Motorola introduced MECL 10K series in 1971 with 2 ns propagation delays. In order to make the circuits comparatively easy to use, edge speed was slowed down to 3.5 ns. Subsequently, the basic MECL 10K series has been expanded by a subset of devices with even greater speed. These subfamilies are 10100 and 10500 series (propagation delay of 2 ns, edge speed of 3.5 ns and flip-flop toggle rate of 160 MHz), 10200 and 10600 series (propagation delay of 1.5 ns, edge speed of 2.5 ns and flip-flop toggle rate of 250 MHz), and 10800 LSI family (propagation delay of 1 - 2.5 ns and edge speed of 3.5 ns) MECL 10KH family was introduced in 1981. This family provides a propagation delay of 1 ns with edge speed at 1.8 ns. These speeds, which were attained with no increase in power over MECL 10K, are due to both advanced circuit design techniques and new oxide isolated process called MOSAIC.

To enhance the existing systems, many of the MECL 10KH devices are pin-out/functional duplications of the MECL 10K family. Also, MECL 10K/10KH are provided with logic levels that are completely compatible with MECL III. Another important feature of MECL 10K/10KH is the significant power reduction over both MECL III and the older MECL II. Because of the power reductions and advanced circuit design techniques, the MECL 10KH family has many new functions not available with the other families. The latest entrant to the ECL family is ECL 100K, having 6-digit part numbers. This family offers functions, in general, different from those offered by 10K series. This family operates with a reduced power supply voltage - 4.5 V, has shorter propagation delay of 0.75 ns, and transition time of 0.7 ns. However, the power consumption per gate is about 40 mW.

### **ELECTRICAL CHARACTERISTICS OF ECL FAMILY**

The input and output levels, and noise margins of ECL gates are given in the Table 1. These values are specified at  $T_A = 25^\circ\text{C}$  and the nominal power supply voltage of  $V_{EE} = -5.2\text{ V}$

TABLE 1: Voltage levels and noise margins of ECL family ICs

Family	$V_{IHmin}$ V	$V_{ILmax}$ V	$V_{OHmax}$ V	$V_{OLmax}$ V	NM Low mV	NM High mV
MECL III	-1.105	-1.475	-1.63	-0.98	155	125
ECL 10K	-1.105	-1.475	-1.63	-0.98	155	125
ECL 10KH	-1.13	-1.48	-1.63	-0.98	150	150
ECL 100K	-1.16	-1.47	-1.62	-1.03	150	130

The noise margin levels are slightly different in High and Low states. This specification by itself does not give complete picture regarding the noise immunity of a system built with a particular set of circuits. In general, noise immunity involves line impedances, circuit output impedances, and propagation delay in addition to noise-margin specifications.

### **Loading Characteristics:**

The differential input to ECL circuits offers several advantages. Its common-mode-rejection feature offers immunity against powersupply noise injection, and its relatively high input impedance makes it possible for any circuit to drive a relatively large number of inputs without deterioration of the guaranteed noise margin. Hence, DC fan out with ECL circuits does not normally present a design problem. Graphs given by the vendor showing the output voltage levels as a function load current can be used to determine the actual output voltages for loads exceeding normal operation.



Family	$I_{ILmax}$ $\mu A$	$I_{IHmax}$ mA	$I_{OLmax}$ mA	$I_{OHmax}$ mA
MECL III	0.5	350	25	25
ECL 10K	0.5	265	22	22
ECL 10KH	0.5	265	22	22
ECL 100K	0.5	265	55	55

### Transition Times and Propagation Delays:

The transition times and delays associated with different ECL families are given in the following.

Family	Prop. delay ns	Edge speed ns	Flip-flop toggle rate MHz
MECL III	1	1	500
ECL 10K (10100&10500)	2	3.5	160
ECL 10K (10200&10600)	1.5	2.5	250
ECL 10K (10800)	1 - 2.5	3.5	NA
ECL 10KH	1	1.8	250
ECL 100K	0.75	0.75	300

The rise and fall times of an ECL output depend mainly on two factors, the termination resistor and the load capacitance. Most of the ECL circuits typically have a 7 ohm output impedance and are relatively unaffected by capacitive loading on positive going output signal. However, the negative-going edge is dependent on the output pull down or termination resistor. Loading close to a ECL output pin will cause an additional propagation delay of 0.1 ns per fan-out load 7 with 50 ohm resistor to -2.0 Vdc or 270 ohms to -5.2 Vdc. The input loading capacitance of an ECL 10K gate is about 2.9 pF. To allow for the IC connector or solder connection and a short stub length 5 to 7 pF is

commonly used in loading calculations.

### **Power Consumption:**

The power dissipation of ECL functional blocks as specified by the manufacturer does not include power dissipated in the output devices due to output termination. The omission of internal output pull-down resistors permits the use of external terminations designed to yield best system performance. To obtain total operating power dissipation of a particular functional block in a system, the dissipation of the output transistor, under load, must be added to the circuit power dissipation. The power dissipation and power-speed products of various ECL families are given in the Table 4

Family	Power dissipation per gate mW	Power-speed product pJ
MECL III	60	60
ECL 10K (10100&10500)	25	50
ECL 10K (10200&10600)	25	37
ECL 10K (10800)	2.3	4.6
ECL 10KH	25	25
ECL 100K	40	30