

## 5.4 SOLUTION OF STATE EQUATIONS

Solution of homogeneous state equations (solution of state equations without input or excitation)

Consider a first order differential equation, with initial condition,  $x(0) = x_0$ .

$$\dot{x} = ax; x(0) = x_0$$

On rearranging equation we get  $\frac{dx}{x} = a dt$  integrating the equation we get,  $\ln x = at + c$

$$X = e^{at} Q_c$$

When  $t=0$ ,  $x = x(0) = e^c$

Given that,  $x(0) = x_0 \cdot e^c = X_0$

The solution of first order differential equation as,

$$x = e^{at} x_0$$

We know that,  $e^x = 1 + \frac{x}{1!} + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots + \frac{x^i}{i!} + \dots$

$$x = \left[ 1 + at + \frac{(at)^2}{2!} + \frac{(at)^3}{3!} + \dots + \frac{(at)^i}{i!} + \dots \right] x_0$$

Consider the state equations without input vector,

$$\dot{X}(t) = A X(t); x(0) = X_0.$$

The solution of the matrix or vector equation can be assumed

$$X(t) = A_0 + A_1 t + A_2 t^2 + \dots$$

Where  $A_0, A_1, A_2, \dots, A_i$  are matrices and the elements of the matrices are constant.

$$X(t) = \left[ I + \frac{A t}{1!} + \frac{A^2 t^2}{2!} + \frac{A^3 t^3}{3!} + \dots + \frac{A^i t^i}{i!} + \dots \right] X_0$$

Where  $I$  is the unit matrix.

Matrix exponential may be written as,

$$e^{At} = I + At + \frac{A^2 t^2}{2!} + \frac{A^3 t^3}{3!} + \dots + \frac{A^i t^i}{i!} + \dots$$

Hence the solution of the state equation is  $X(t) = e^{At} X_0$ . The matrix  $e^{At}$  is called state transition matrix and denoted by  $\Phi(t)$ .

## PROPERTIES OF STATE TRANSITION MATRIX

1.  $(\cdot)$
2.  $(\cdot)(\cdot) [(\cdot)]$
3.  $(\cdot)^{(\cdot)}(\cdot)(\cdot)(\cdot)$

## COMPUTATION OF STATE TRANSITION MATRIX

Method 1: Computation of  $e^{A_c}$  using matrix exponential

In this method the  $e^{A_c}$  is computed using the matrix exponential of equation

$$e^{At} = \left[ I + At + \frac{1}{2!} A^2 t^2 + \frac{1}{3!} A^3 t^3 + \dots + \frac{1}{i!} A^i t^i \right]$$

Where,

$e^{A_c}$  state transition matrix of order  $n \times n$

$A$  = System matrix of order  $n \times n$

$I$  = Unit matrix of order  $n \times n$

Method 2: Computation of state transition matrix by Laplace transforms method

Consider the state equation without input vector  $\dot{X}(t) = A X(t)$

On taking Laplace transform of above equation,

$$X(s) = (sI - A)^{-1} X(0)$$

On taking inverse Laplace transform

$$X(t) = L^{-1}[(sI - A)^{-1}] X(0)$$

On comparing above equation with state equation

$$X(t) = e^{At} x_0$$

$$e^{At} = L^{-1}[(sI - A)^{-1}]$$

$$L[e^{At}] = L[p(t)] = p(s)$$

Where  $(\cdot)$   $(\cdot)$  it is called resolvent matrix