

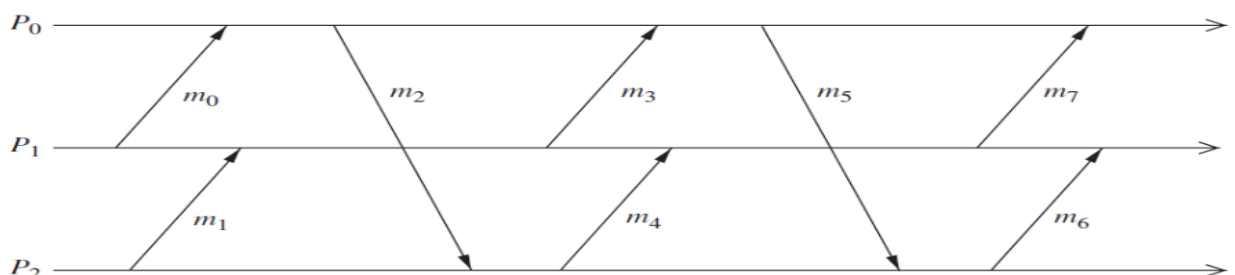
## LOG-BASED ROLLBACK RECOVERY

A log-based rollback recovery makes use of deterministic and nondeterministic events in a computation.

### Deterministic and non-deterministic events

- Log-based rollback recovery exploits the fact that a process execution can be modeled as a sequence of deterministic state intervals, each starting with the execution of a non-deterministic event.
- A non-deterministic event can be the receipt of a message from another process or an event internal to the process.
- Note that a message send event is *not* a non-deterministic event.
- For example, in Figure, the execution of process  $P_0$  is a sequence of four deterministic intervals. The first one starts with the creation of the process, while the remaining three start with the receipt of messages  $m_0$ ,  $m_3$ , and  $m_7$ , respectively.
- Send event of message  $m_2$  is uniquely determined by the initial state of  $P_0$  and by the receipt of message  $m_0$ , and is therefore not a non-deterministic event.
- Log-based rollback recovery assumes that all non-deterministic events can be identified and their corresponding determinants can be logged into the stable storage.
- Determinant: the information need to “replay” the occurrence of a non-deterministic event (e.g., message reception).
- During failure-free operation, each process logs the determinants of all non-deterministic events that it observes onto the stable storage. Additionally, each process also takes checkpoints to reduce the extent of rollback during recovery.

### Log-based Rollback Recovery



### The no-orphans consistency condition

Let  $e$  be a non-deterministic event that occurs at process  $p$ .

We define the following:

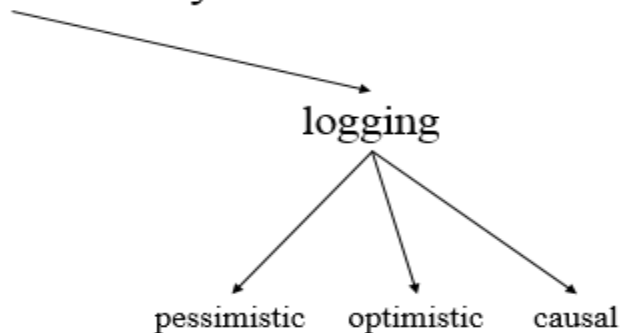
- **Depend( $e$ )**: the set of processes that are affected by a non-deterministic event  $e$ .
- **Log( $e$ )**: the set of processes that have logged a copy of  $e$ 's determinant in their volatile memory.
- **Stable( $e$ )**: a predicate that is true if  $e$ 's determinant is logged on the stable storage.

### *always-no-orphans* condition

$$- \forall(e) : \neg \text{Stable}(e) \Rightarrow \text{Depend}(e) \subseteq \text{Log}(e)$$

### Types

#### Rollback-Recovery



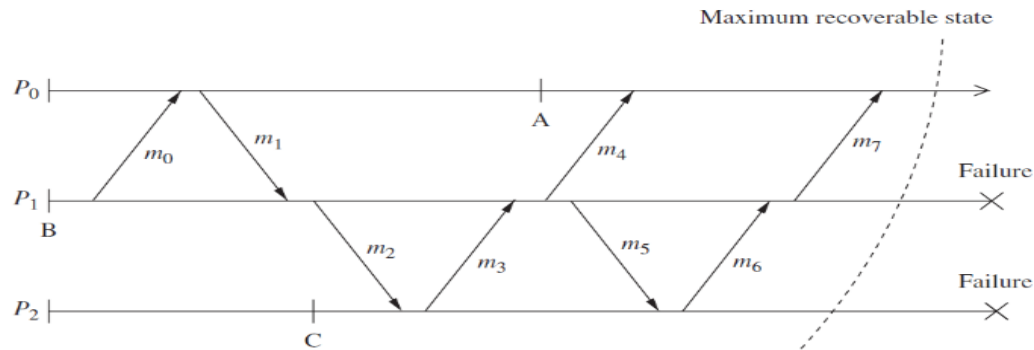
#### 1. Pessimistic Logging

- Pessimistic logging protocols assume that a failure can occur after any non-deterministic event in the computation. However, in reality failures are rare
- Pessimistic protocols implement the following property, often referred to as *synchronous logging*, which is a stronger than the always-no-orphans condition
- *Synchronous logging*
  - $\forall e: \neg \text{Stable}(e) \Rightarrow |\text{Depend}(e)| = 0$
- That is, if an event has not been logged on the stable storage, then no process can depend on it.

#### Example:

Suppose processes  $P1$  and  $P2$  fail as shown, restart from checkpoints B and C, and roll forward using their determinant logs to deliver again the same sequence of messages as in the pre-failure execution

- Once the recovery is complete, both processes will be consistent with the state of  $P_0$  that includes the receipt of message  $m_7$  from  $P_1$

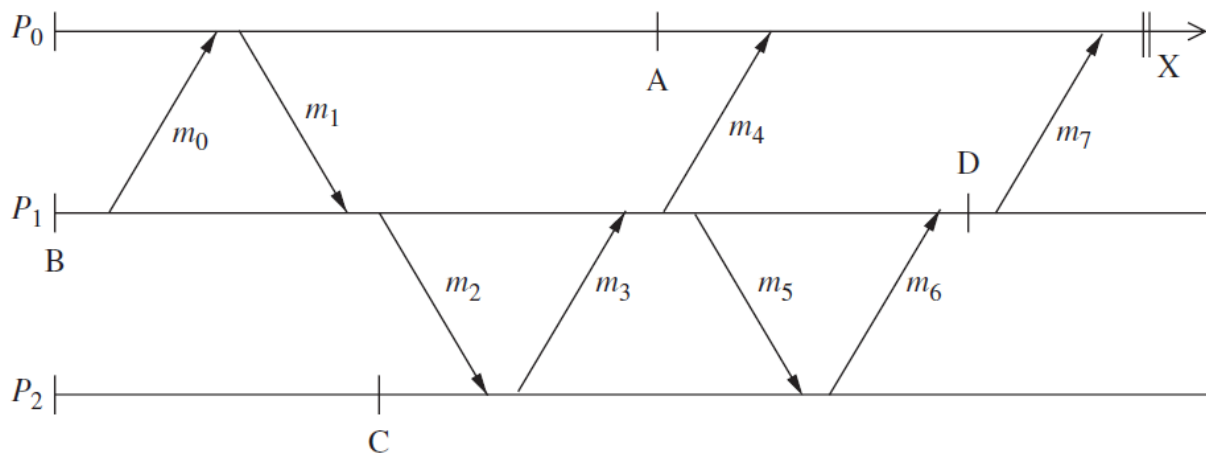


- **Disadvantage:** performance penalty for synchronous logging
- **Advantages:**
  - immediate output commit
  - restart from most recent checkpoint
  - recovery limited to failed process(es)
  - simple garbage collection
- Some pessimistic logging systems reduce the overhead of synchronous logging without relying on hardware. For example, the *sender-based message logging* (SBML) protocol keeps the determinants corresponding to the delivery of each message  $m$  in the volatile memory of its sender.
- The *sender-based message logging* (SBML) protocol
  - Two steps.
    1. First, before sending  $m$ , the sender logs its content in volatile memory.
    2. Then, when the receiver of  $m$  responds with an acknowledgment that includes the order in which the message was delivered, the sender adds to the determinant the ordering information.

## 2. Optimistic Logging

- Processes log determinants asynchronously to the stable storage
- Optimistically assume that logging will be complete before a failure occurs
- Do not implement the *always-no-orphans* condition

- To perform rollbacks correctly, optimistic logging protocols track causal dependencies during failure free execution
- Optimistic logging protocols require a non-trivial garbage collection scheme
- Pessimistic protocols need only keep the most recent checkpoint of each process, whereas optimistic protocols may need to keep multiple checkpoints for each process

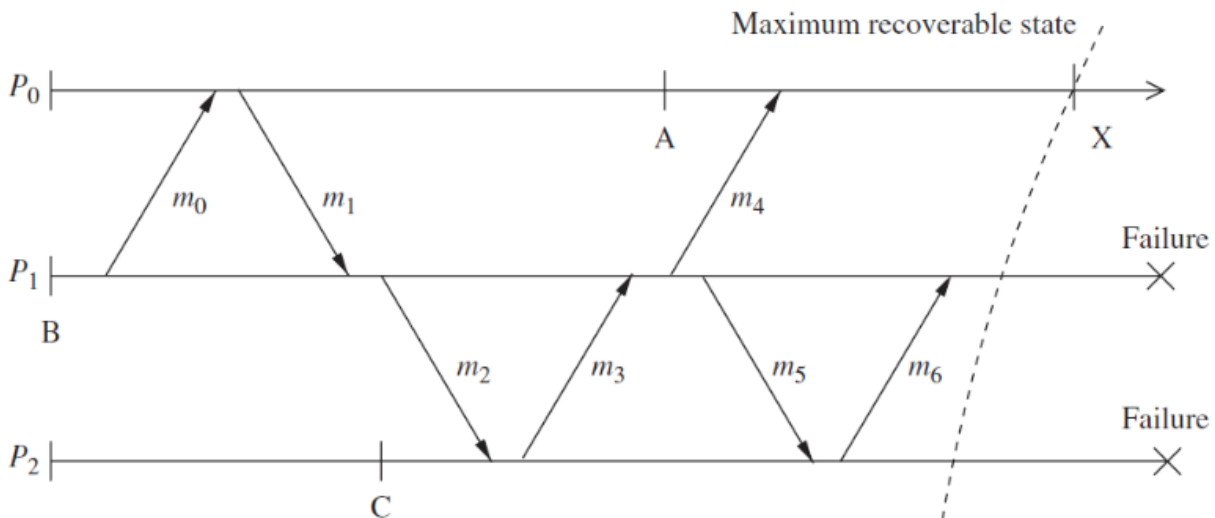


- Consider the example shown in Figure. Suppose process  $P_2$  fails before the determinant for  $m_5$  is logged to the stable storage. Process  $P_1$  then becomes an orphan process and must roll back to undo the effects of receiving the orphan message  $m_6$ . The rollback of  $P_1$  further forces  $P_0$  to roll back to undo the effects of receiving message  $m_7$ .
- **Advantage:** better performance in failure-free execution
- **Disadvantages:**
  - coordination required on output commit
  - more complex garbage collection
- Since determinants are logged asynchronously, output commit in optimistic logging protocols requires a guarantee that no failure scenario can revoke the output. For example, if process  $P_0$  needs to commit output at state X, it must log messages  $m_4$  and  $m_7$  to the stable storage and ask  $P_2$  to log  $m_2$  and  $m_5$ . In this case, if any process fails, the computation can be reconstructed up to state X.

### 3. Causal Logging

- Combines the advantages of both pessimistic and optimistic logging at the expense of a more complex recovery protocol

- Like optimistic logging, it does not require synchronous access to the stable storage except during output commit
- Like pessimistic logging, it allows each process to commit output independently and never creates orphans, thus isolating processes from the effects of failures at other processes
- Make sure that the always-no-orphans property holds
- Each process maintains information about all the events that have causally affected its state



- Consider the example in Figure Messages  $m_5$  and  $m_6$  are likely to be lost on the failures of  $P_1$  and  $P_2$  at the indicated instants. Process
- $P_0$  at state X will have logged the determinants of the nondeterministic events that causally precede its state according to Lamport's *happened-before* relation.
- These events consist of the delivery of messages  $m_0$ ,  $m_1$ ,  $m_2$ ,  $m_3$ , and  $m_4$ .
- The determinant of each of these non-deterministic events is either logged on the stable storage or is available in the volatile log of process  $P_0$ .
- The determinant of each of these events contains the order in which its original receiver delivered the corresponding message.
- The message sender, as in sender-based message logging, logs the message content. Thus, process  $P_0$  will be able to "guide" the recovery of  $P_1$  and  $P_2$  since it knows the order in which  $P_1$  should replay messages  $m_1$  and  $m_3$  to reach the state from which  $P_1$  sent message  $m_4$ .

- Similarly,  $P_0$  has the order in which  $P_2$  should replay message  $m_2$  to be consistent with both  $P_0$  and  $P_1$ .
- The content of these messages is obtained from the sender log of  $P_0$  or regenerated deterministically during the recovery of  $P_1$  and  $P_2$ .
- Note that information about messages  $m_5$  and  $m_6$  is lost due to failures. These messages may be resent after recovery possibly in a different order.
- However, since they did not causally affect the surviving process or the outside world, the resulting state is consistent.
- Each process maintains information about all the events that have causally affected its state.

