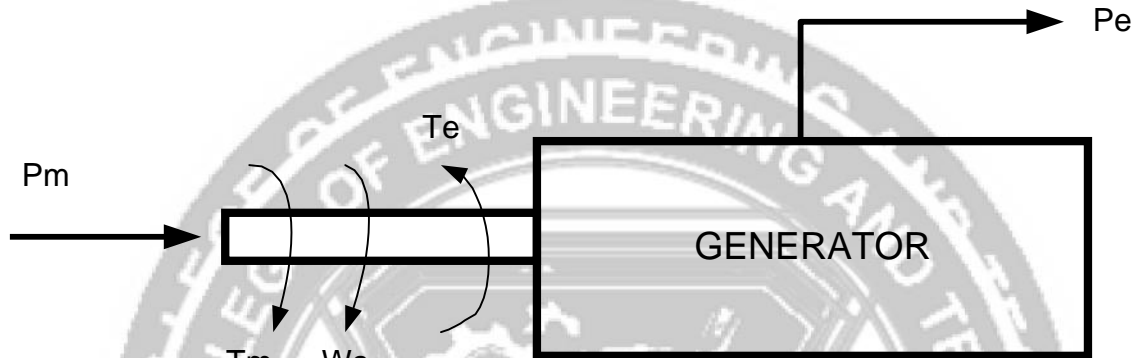


Swing Equation:-

(Fig.-1 Flow of power in a synchronous generator)

Consider a synchronous generator developing an electromagnetic torque T_e (and a corresponding electromagnetic power P_e) while operating at the synchronous speed w_s . If the input torque provided by the prime mover, at the generator shaft is T_i , then under steady state conditions (i.e., without any disturbance).

$$T_e = T_i \dots\dots\dots (10)$$

Here we have neglected any retarding torque due to rotational losses. Therefore we have

$$T_e \omega_s = T_i \omega_s \dots\dots\dots (11)$$

And $T_e \omega_s - T_i \omega_s = P_i - P_e = 0 \dots\dots\dots (12)$

When a change in load or a fault occurs, then input power P_i is not equal to P_e . Therefore left side of equation is not zero and an accelerating torque comes into play. If P_a is the accelerating (or decelerating) power, then

$$P_i - P_e = M \cdot \frac{d^2\theta_e}{dt^2} + D \frac{d\theta_e}{dt} = P_a \dots\dots\dots (13)$$

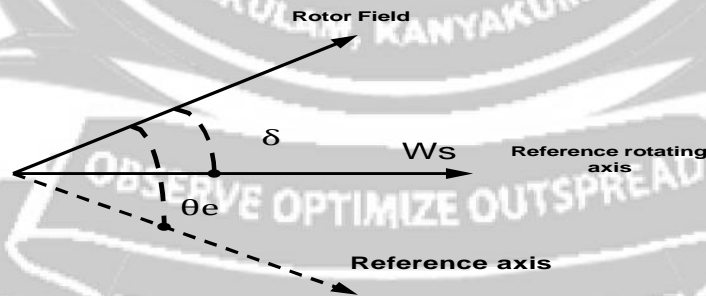
Where D = damping coefficient
 θ_e = electrical angular position of the rotor

It is more convenient to measure the angular position of the rotor with respect to a synchronously rotating frame of reference. Let

$$\theta_e = \theta_p - \omega_s \cdot t \dots\dots\dots (14)$$

So $\frac{d^2\theta_e}{dt^2} = \frac{d^2\theta_p}{dt^2} \dots\dots\dots (15)$

Where θ_p is power angle of synchronous machine.



(Fig.2 Angular Position of rotor with respect to reference axis)

Neglecting damping (i.e., $D = 0$) and substituting equation (15) in equation (13) we get

$$M \cdot \frac{d^2\delta}{dt^2} = P_i - P_e \text{ MW} \dots\dots\dots (16)$$

Using equation (6) and (16), we get

$$\frac{GH}{\pi f} \cdot \frac{d^2\delta}{dt^2} = P_i - P_e \text{ MW} \dots\dots\dots (17)$$

Dividing throughout by G, the MVA rating of the machine,

$$M_{(pu)} \cdot \frac{d^2\delta}{dt^2} = (P_i - P_e) \text{ pu} \dots\dots\dots (18)$$

Where

$$M_{(pu)} = \frac{H}{\pi f} \dots\dots\dots (19)$$

or

$$\frac{H}{\pi f} \cdot \frac{d^2\delta}{dt^2} = (P_i - P_e) \text{ pu} \dots\dots\dots (20)$$

Equation (20) is called **Swing Equation**. It describes the rotor dynamics for a synchronous machine. Damping must be considered in dynamic stability study.

Multi Machine System:-

In a multi machine system a common base must be selected. Let

$$G_{\text{machine}} = \text{machine rating (base)}$$

$$G_{\text{system}} = \text{system base}$$

Equation (20) can be written as:

$$\frac{G_{\text{machine}}}{G_{\text{system}}} \left(\frac{H_{\text{machine}}}{f} \right) \frac{d^2\delta}{dt^2} = (P_i - P_e) \cdot \frac{G_{\text{machine}}}{G_{\text{system}}} \dots\dots\dots (21)$$

So

$$\left(\frac{H_{\text{system}}}{f} \right) \frac{d^2\delta}{dt^2} = (P_i - P_e) \text{ pu on system base} \dots\dots\dots (22)$$

Where

$$H_{\text{system}} = \frac{G_{\text{machine}}}{G_{\text{system}}} \cdot H_{\text{machine}} \dots\dots\dots (23)$$

= machine inertia constant in system base

Machines Swinging in Unison (Coherently) :-

Let us consider the swing equations of two machines on a common system base, i.e.,

$$\frac{H_1}{\pi f} \cdot \frac{d^2\delta_1}{dt^2} = (P_{i1} - P_{e1}) \dots\dots\dots (24)$$

$$\frac{H_2}{\pi f} \cdot \frac{d^2\delta_2}{dt^2} = (P_{i2} - P_{e2}) \dots\dots\dots (25)$$

Since the machines rotor swing in unison,

$$\delta_1 = \delta_2 = \dots\dots\dots (26)$$

Adding equations (24) and (25) and substituting equation (26), we get

$$\frac{H_{eq}}{f} \cdot \frac{d^2\delta}{dt^2} = (P_i - P_e) \dots\dots\dots (27)$$

Where

$$P_i = P_{i1} + P_{i2}$$

$$P_e = P_{e1} + P_{e2}$$

$$H_{eq} = H_1 + H_2$$

Equivalent inertia H_{eq} can be expressed as:

$$H_{eq} = \left(\frac{G_{1,machine}}{G_{System}} \right) \cdot H_{1,machine} + \left(\frac{G_{2,machine}}{G_{system}} \right) \cdot H_{2,machine} \dots\dots\dots (28)$$

Example1:-

A 60 Hz, 4 pole turbo-generator rated 100MVA, 13.8 KV has inertia constant of 10 MJ/MVA.

- (a) Find stored energy in the rotor at synchronous speed.
- (b) If the input to the generator is suddenly raised to 60 MW for an electrical load of 50 MW, find rotor acceleration.
- (c) If the rotor acceleration calculated in part (b) is maintained for 12 cycles, find the change in torque angle and rotor speed in rpm at the end of this period.
- (d) Another generator 150 MVA, having inertia constant 4 MJ/MVA is put in parallel with above generator. Find the inertia constant for the equivalent generator on a base 50 MVA.

Solution:-

- (a) Stored energy = GH
 = 100MVA x 10MJ/MVA
 = 1000MJ
- (b) $P_a = P_i - P_e = 60 - 50 = 10\text{MW}$
 We know, $M = \frac{GH}{180f} = \frac{100 \times 10}{180 \times 60} = \frac{5}{54} \text{ MJ.sec/elect.deg.}$

$$\text{Now } M_i \frac{d^2\delta}{dt^2} = P_i - P_e = P_a$$

$$\Rightarrow \frac{5}{54} \frac{d^2\delta}{dt^2} = 10$$

$$\Rightarrow \frac{d^2\delta}{dt^2} = \frac{10 \times 54}{5} = 108 \text{ elect.deg./sec}^2$$

$$\text{So, } \alpha = \text{acceleration} = 108 \text{ elect.deg./sec}^2$$

$$(c) 12 \text{ cycles} = 12/60 = 0.2 \text{ sec.}$$

$$\text{Change in } \delta = \frac{1}{2} \alpha t^2 = \frac{1}{2} \cdot 108 \cdot (0.2)^2 = 2.16 \text{ elect.deg}$$

$$\begin{aligned} \text{Now } \alpha &= 108 \text{ elect.deg./sec}^2 \\ &= 60 \times (108/360^\circ) \text{ rpm/sec} \\ &= 18 \text{ rpm/sec} \end{aligned}$$

Hence rotor speed at the end of 12 cycles

$$\begin{aligned} &= \frac{120f}{P} + \alpha \cdot \Delta t \\ &= \left(\frac{120 \times 60}{4} + 18 \times 0.2 \right) \text{ rpm} \\ &= 1803.6 \text{ rpm.} \end{aligned}$$

$$(d) H_{eq} = \frac{H_1 G_1}{G_b} + \frac{H_2 G_2}{G_b} = \frac{10 \times 100}{50} + \frac{4 \times 150}{50} = 32 \text{ MJ/MVA}$$