

5.5 LTI SYSTEM ANALYSIS USING DTFT

Output of LTI system is given by linear convolution

$$y(n) = \sum_{k=-\infty}^{\infty} h(k)x(n-k)$$

Let the system be excited by the sinusoidal or phaser $e^{j\omega n}$.

$$\therefore x(n) = e^{j\omega n} \text{ for } -\infty < n < \infty$$

Hence the signal is complex in nature .It has unit amplitude and frequency is ' ω '.The output is given by

$$\begin{aligned} y(n) &= \sum_{k=-\infty}^{\infty} h(k)e^{j\omega(n-k)} \\ &= \sum_{k=-\infty}^{\infty} h(k)e^{j\omega n} \cdot e^{-j\omega k} \\ &= \left[\sum_{k=-\infty}^{\infty} h(k)e^{-j\omega k} \right] e^{j\omega n} \\ &= H(\omega)e^{j\omega n} \end{aligned}$$

$$H(\omega) = \sum_{k=-\infty}^{\infty} h(k)e^{-j\omega k}$$

$H(\omega)$ is the Fourier transform of $h(k)$ and $h(k)$ is the unit sample response. $H(\omega)$ is called the transfer function of the system. $H(\omega)$ is complex valued function of ω in the range $-\pi \leq \omega \leq \pi$.The transfer function of $H(\omega)$ can be expressed in polar form as

$$H(\omega) = |H(\omega)|e^{j\angle H(\omega)}$$

$|H(\omega)|$ is the magnitude of $H(\omega)$

$\angle H(\omega)$ is the angle of $H(\omega)$

LTI SYSTEM ANALYSIS USING Z-TRANSFORM

The Z-Transform of impulse response is called transfer or system function $H(Z)$.

$$Y(Z) = X(Z)H(Z)$$

General form of LCCDE

$$\sum_{k=0}^N a_k y[n-k] = \sum_{k=0}^M b_k x[n-k]$$

$$\sum_{k=0}^N a_k z^{-k} Y(z) = \sum_{k=0}^M b_k z^{-k} X(z)$$

Computing the Z-Transform

$$H(z) = \frac{Y(z)}{X(z)} = \frac{\sum_{k=0}^M b_k z^{-k}}{\sum_{k=0}^N a_k z^{-k}}$$

Example 1: Consider the system described by the difference equation.

$$y[n] = x[n] + \frac{1}{3}x[n-1] + \frac{5}{4}y[n-1] - \frac{1}{2}y[n-2] + \frac{1}{16}y[n-3]$$

Solution:

$$y[n] = x[n] + \frac{1}{3}x[n-1] + \frac{5}{4}y[n-1] - \frac{1}{2}y[n-2] + \frac{1}{16}y[n-3]$$

Here $N = 3$, $M = 1$. Order 3 homogeneous equation:

$$y[n] - \frac{5}{4}y[n-1] + \frac{1}{2}y[n-2] - \frac{1}{16}y[n-3] = 0 \quad n \geq 2$$

The characteristic equation:

$$1 - \frac{5}{4}a^{-1} + \frac{1}{2}a^{-2} - \frac{1}{16}a^{-3} = 0$$

The roots of this third order polynomial is: $a_1 = a_2 = 1/2$ $a_3 = 1/4$ and

$$y_h[n] = h[n] = A_1\left(\frac{1}{2}\right)^n + A_2n\left(\frac{1}{2}\right)^n + A_3\left(\frac{1}{4}\right)^n, \quad n \geq 2$$

Let us assume $y[-1] = 0$ then (3.52) for this case becomes:

$$\begin{bmatrix} a_0 & 0 \\ a_1 & a_0 \end{bmatrix} \cdot \begin{bmatrix} y[0] \\ y[1] \end{bmatrix} = \begin{bmatrix} b_0 \\ b_1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 \\ -5/4 & 1 \end{bmatrix} \cdot \begin{bmatrix} y[0] \\ y[1] \end{bmatrix} = \begin{bmatrix} 1 \\ 1/3 \end{bmatrix} \Rightarrow y[0] = 1; y[1] = 19/12$$

with these we have the impulse response of this system:

$$h[n] = -\frac{4}{3}\left(\frac{1}{2}\right)^n + \frac{10}{3}n\left(\frac{1}{2}\right)^n + \frac{7}{3}\left(\frac{1}{4}\right)^n, \quad n \geq 0$$

